Computer Vision as Multimedia Translation and Data Mining

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Visual Representation

Semantic Representation



A tiger lying in the grass

Visual Representation Semantic Representation



Auto-Annotating Images

Finding words for the images





Barnard, Forsyth (ICCV 2001), Barnard, Duygulu, Forsyth (CVPR 2001)

Other related work : Maron 98, Mori 99

Annotation vs Recognition



Recognition



Semantic representation includes not only what is there, but where it is

General Approach

Learn models for annotation and recognition from large image data sets with associated text

[ICCV 2000, ECCV, 2002, JMLR 2003]

Key Point

Learn from data without explicit correspondence between image components



Data with correspondence ambiguity is common Images with associated text Video (which frame (entity) goes with which speech or text) Bioinformatics

Key Point (cont)

Trade quality for quantity (and realism)

Sources of information

A word (tiger) is much more likely than chance to have something to do with the image

If a word refers to something in the image (tiger), it is less likely to refer to something else

Relationship between visual information and words has structure across images

Statistical Machine Translation

Data: Aligned sentences, but word correspondences are unknown

"the beautiful sun"



Brown, Della Pietra, Della Pietra & Mercer 93

Multimedia Translation



Approaches

Discretize (tokenize) blobs [Duygulu, Barnard, de Freitas, Forsyth, ECCV 02]

Simultaneously learn blob models and translation [Barnard et al, JMLR 03]

Multiple instance learning with support vector machines [Andrews et al, NIPS 02]

Integrate context into features [Barnard et al. CVPR 03] and into the model [Carbenetto et al. 03]

Composite models [Barnard et al. CVPR 03, Wachsmuth et al, 03]

Corel Database



392 CD's, each consisting of 100 annotated images.

Input

Image

processing*



sun sky waves sea

Each region is described by a set of features

- Region size
- Position
- Color
- Oriented energy (12 filters)
- Simple shape features

*Thanks to Blobworld team [Carson, Belongie, Greenspan, Malik], N-cuts team [Shi, Tal, Malik]

Discrete Model [ECCV 02]

Straightforward adaptation of machine translation

Need to vector quantize blobs (simple but better to simultaneously learn blob model)



city mountain sky sun



jet plane sky



cat forest grass tiger



beach people sun water





cat grass tiger water

Dictionary



Initialization

Initialize translation table to blob-word cooccurrences (empirical joint distribution of blobs and words)



Expectation Maximization

Given the translation probabilities estimate the correspondences Given the correspondences estimate the translation probabilities

Why does this work?

Co-occurrence is a sensible starting point

EM process sharpens probabilities by integrating dictionary with constrained choices





Generate words by frequency table

Generate blobs by Gaussian over features

(Conditionally independent given node)





Labeling Regions

Segment the image

Use model to compute P(word | region)

Labeling Regions



Labeling Regions

Display only maximal probable word







Measuring Performance

First strategy--score by hand

Second strategy--use annotation performance as a proxy.

First Strategy Score by hand



Average performance is four times better than guessing the most common word

("water")

Second Strategy Use Annotation





tiger cat grass water

Automatic : Don't need to do by hand

Annotating Images















Measuring Annotation Performance





GRASS TIGER CAT FOREST

En State in the



CAT HORSE GRASS WATER

Measuring Annotation Performance



Exploiting Word Prediction

Model Selection Segmentation Feature choices

Blobworld segmentations



N-cuts segmentations



Comments on recognition vs annotations

Learning on data without correspondence is a good trick BUT there are fundamental problems

Intuitively the words are generated through the the parts (regions, groups), but the error function refers to the whole.

Need a better theory of how to link the two.

Integrating Supervision

Estimate where a minimal amount of supervision can be most helpful.



Integrating Feature Selection

Propose good features to differentiate words that are not distinguishable (e.g., eagle and jet)





Integrating Vision Levels

Word prediction gives a new way to think about integrating high and low level vision processes

Region Merging



Region Merging

Use word posteriors to propose region merges

Recompute descriptors for the conglomerate object (color histograms, shape descriptors)

Have the system learn what kinds of "familiar configurations" are useful (i.e. lead to better word prediction)

Preliminary Experiment [CVPR, 03]





Good merge

Poor merge

More Complex Semantics

Current system links uniform blobs to simple nouns

Working towards linking groups of blobs to nouns, relations to prepositions, and attributes to adjectives

Summary

Recognition on the large scale

Unsupervised - label without labeled training data

Learn what to recognize

Semantic evaluation of vision tools

Integrating vision processing levels

Bottom Line

Recognition as machine translation

Machine vision as data-mining

















