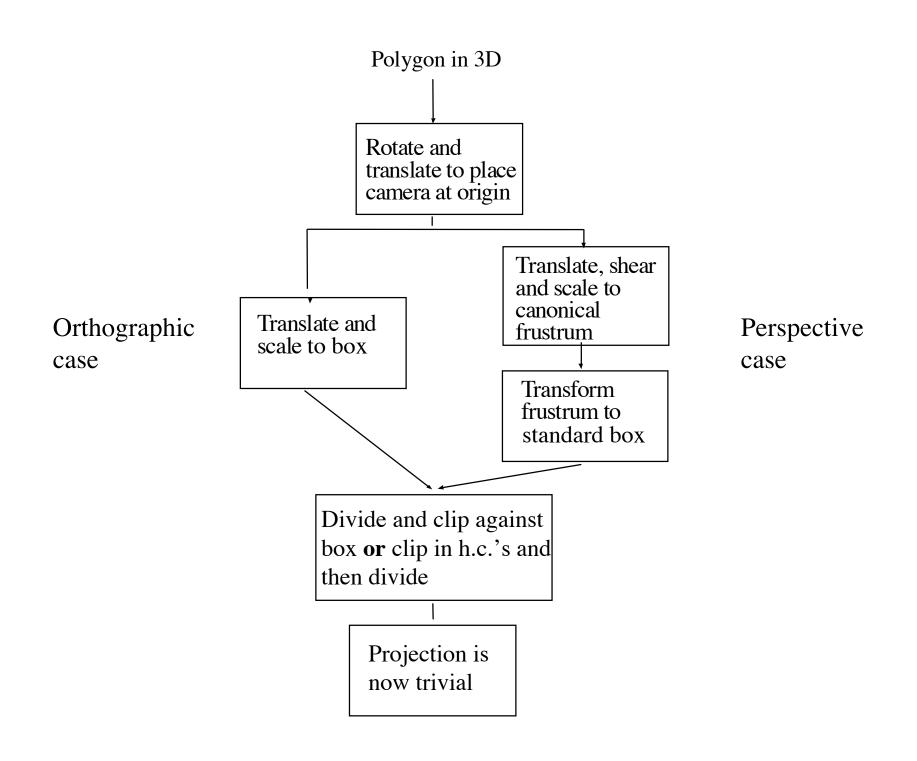
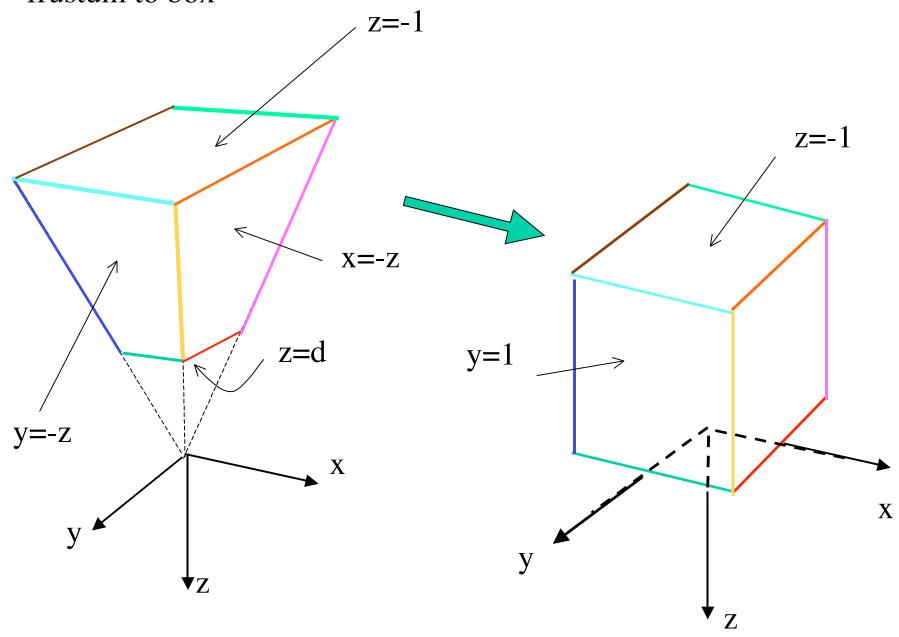
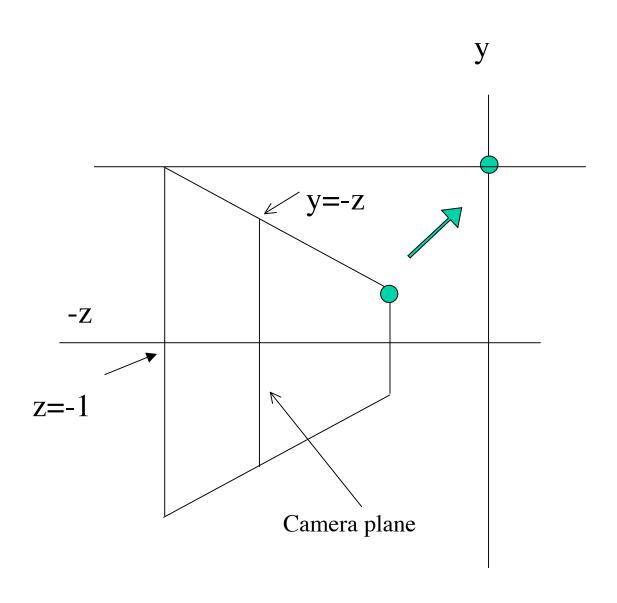
Plan B: Clipping in homogenous coords

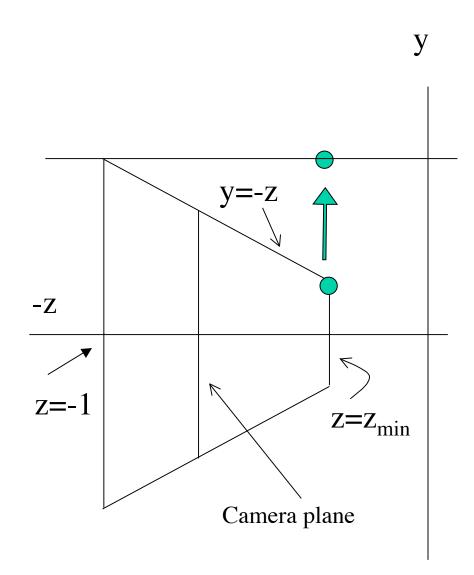
- For any camera, can turn the view frustrum into a regular parallelepiped (box). We will use the box bounded by $x = \pm 1$, $y = \pm 1$, z = -1, and z = 0.
- Advantages
 - Simplified clipping in homogenous coordinates
 - Extends to cases where we use homogenous coordinates to represent additional information (and W could be negative).
 - Can simplify visibility algorithms.
- Approach: clever use of homogenous coordinates

(Will be needed for assignment three)









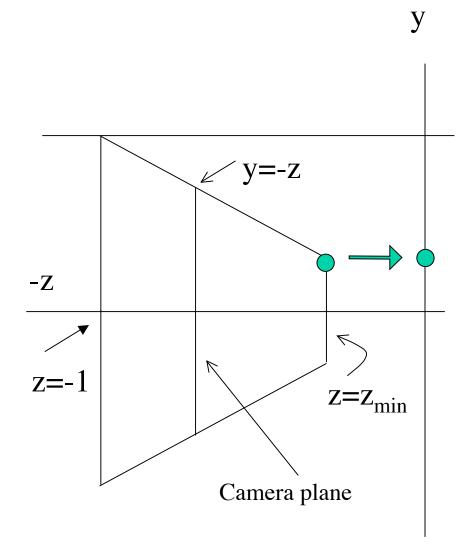
On top, y-->1, so scaling is (1/y)Recall that y=-x there.

On bottom, y-->-1 so scaling is (-1/y). Recall that y=x there.

So scaling is y' = y/(-z)

Similarly, x' = x/(-z)

Transformation is **non-linear**, but in h.c., can use w=-z.



For z, we shift near plane to origin. But now box is too small. Specifically it has z dimension $(1 \square z_{min})$ (recall z_{min} is negative)

So we have an extra scale factor $1/(1+z_{min})$ and thus $z'=(z-z_{min})/(1+z_{min})$

But we want x and y to work nicely in h.c., we use

$$z' = ((z - z_{min}) / (1 + z_{min}))/(-z)$$

(Depths **also** transform **non-linearly**)

In h.c.,

$$x=>x$$
 $y=>y$
 $z=>(z - z_{min}) / (1 + z_{min})$
 $1=>-z$

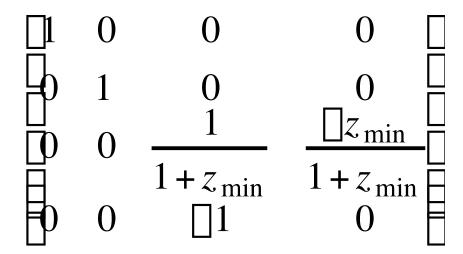
So, the matrix is



In h.c.,

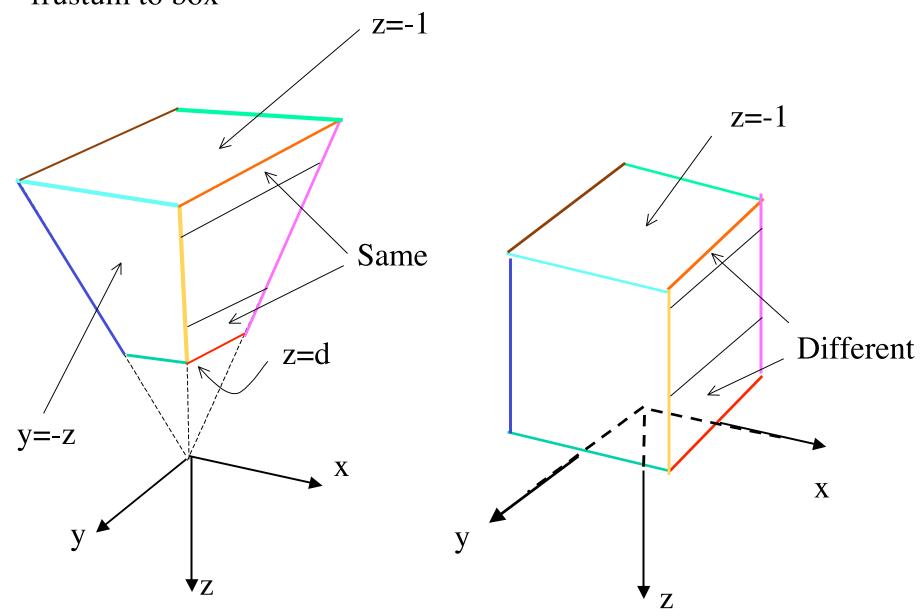
$$x=>x$$
 $y=>y$
 $z=>(z - z_{min}) / (1 + z_{min})$
 $1=>-z$

So, the matrix is



Mapping to standard parallel projection view volume (additional comments)

- The mapping from $[z_{min}, -1]$ to [0,-1] is non-linear. (Of course, there exists a linear mapping, but not if we want everything else to work out nicely in h.c.).
- So a change in depth of \triangle D at the near plane maps to a larger depth difference in screen coordinates than the same \triangle D at the far plane.
- But order is preserved (important!); the function is monotonic (proof?).
- And lines are still lines (proof?) and planes are still planes (important!).



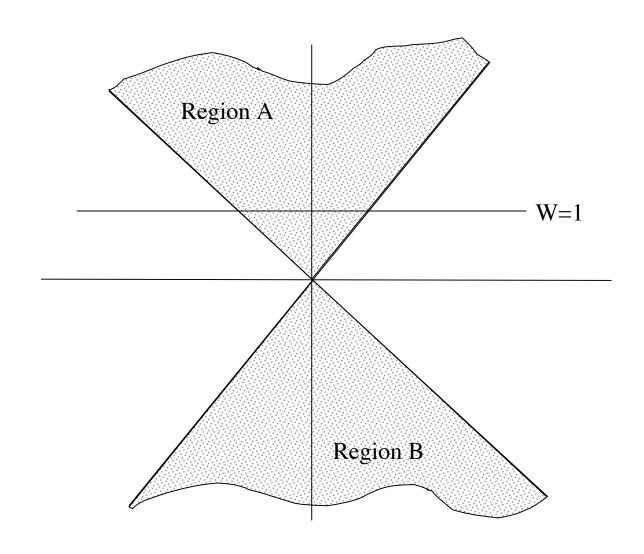
- We have a cube, but its representation is in h.c., so we must divide
- Clipping requires a test for inside or out; in 2D, we used x>xmax, x<xmin, etc.
- In 3D, for clipping against the cube, we could use x>1, x<-1, etc.
- But to do this, we would have to convert to cartesian coords by division.
- Dividing before clipping is inefficient if many points are excluded, so we clip in h.c.'s.

- Write h.c.'s in caps, ordinary coords in lowercase.
- Consider case x>1, x<-1
- Rearrange clipping inequalities:

$$\begin{array}{ccc} \boxed{X} \\ \boxed{W} \end{array} > 1 & X > W, & X < W, \\ \boxed{X} \\ \boxed{W} \end{array} > 0 & X < W, \\ X > W, & X < W, \\ X > W, & X > W, \\ W > 0 & W < 0 \end{array}$$

(So far W is positive, but negatives occur if we further overload the use of h.c.'s)

The clipping volume in cross section



- If we know that W is positive (the case so far!), simply clip against region A
- If we are using the h.c. for additional deferred division, then W can be negative.
- If W is negative, then we use region B. The clipping can be done by negating the point, and clipping against A, due to the nature of A and B.
- Case where object has both positive and negative W is a little more complex.
- Notice that the actual clipping computations are not that different from the case in Plan A---no free lunch!