#### B-splines - I

- Now consider stitching together curves which do not necessarily pass through the control points.
- Local control
- Blending functions are non-zero over limited range--thus they are like "switches"
- In the simplest case of uniformly spaced control points, the blending functions will be shifted versions of the same function.

## B-splines - II

• Curve (general case):

$$X(t) = \prod_{k=0}^{n} P_k B_{k,d}(t)$$

• The "degree parameter" d is:

$$2 \square d \square n + 1$$

- Note the "degree" of the polynomial is d-1 (not d).
- We have n+1 control points, and n+1 blending functions. The most common case is d=4.

- Knots
  - parameter values where curve segments meet
- There are n+d+1 knots for B-spline

$$(t_0, t_1, ..., t_{n+d})$$
where  $t_0 \square t_1 \square ... \square t_{n+d}$ 

- B-spline is defined for the range  $(t_{d\square 1},...,t_{n+1})$ 
  - So all curve points have contributions from d control points
  - All sections of curves behave the same (later we will see how to interpolate the endpoints.
- Blending functions for degree parameter d have support (are non-zero) for d subintervals.

Blending functions

$$B_{k,1}(t) = \begin{bmatrix} 1 & t_k & | & t & | & t_{k+1} \\ 0 & \text{otherwise} \end{bmatrix}$$

$$B_{k,d}(t) = \begin{bmatrix} t & | & t_k \\ | & t_k & | & | \\ | & t_{k+d-1} & | & t_k & | \\ | & t_{k+d-1} & | & t_k & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+d-1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | & t_{k+1} & | \\ | & t_{k+1} & | &$$

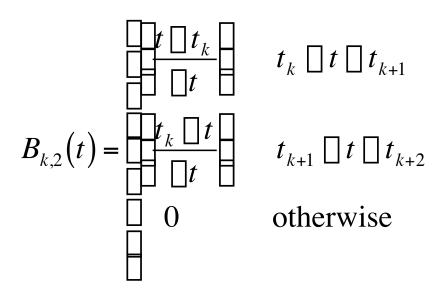
• If knots are repeated we use 0/0=0

$$B_{k,d}(t) = \begin{bmatrix} t & t & t_k &$$

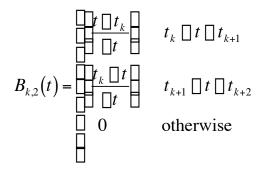
$$B_{k,2}(t) = ?$$

$$B_{k,d}(t) = \begin{bmatrix} t & t & t_k \\ \hline t_{k+d\square 1} & t_k \end{bmatrix} B_{k,d\square 1}(t) + \begin{bmatrix} t_{k+d} & t_k \\ \hline t_{k+d} & t_{k+1} \end{bmatrix} B_{k+1,d\square 1}(t)$$

$$B_{k,1}(t) = \begin{bmatrix} 1 & t_k & t \\ \hline 0 & \text{otherwise} \end{bmatrix}$$

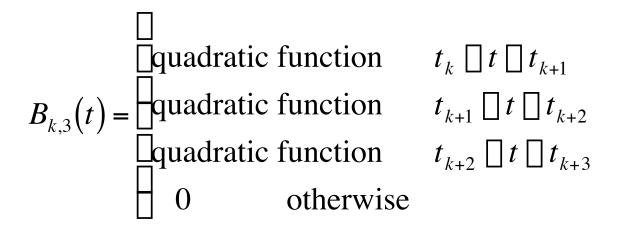


$$B_{k,d}(t) = \begin{bmatrix} t & t & t_k &$$



$$B_{k,3}(t) = ?$$

$$B_{k,d}(t) = \begin{bmatrix} t & t & t_k &$$



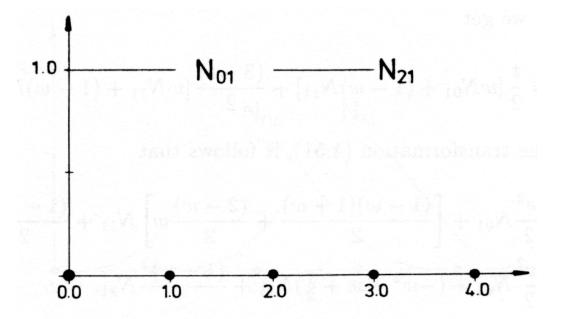


Fig. 4.22c. The B-splines  $N_{01}$ ,  $N_{21}$ .

These figures show blending functions with a uniform knot vector, knots at 0, 1, 2, etc.

Note that N is the same as our B

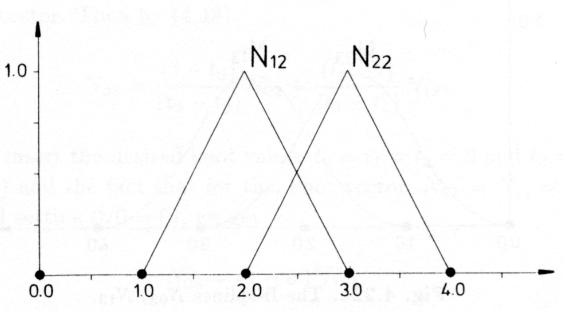
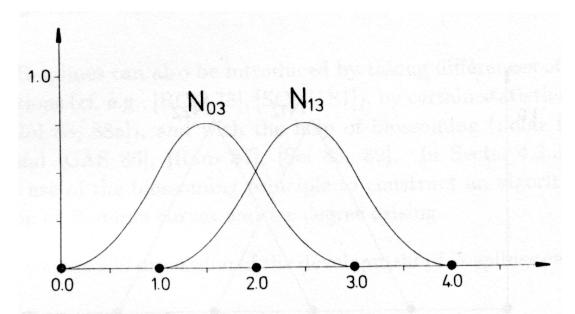
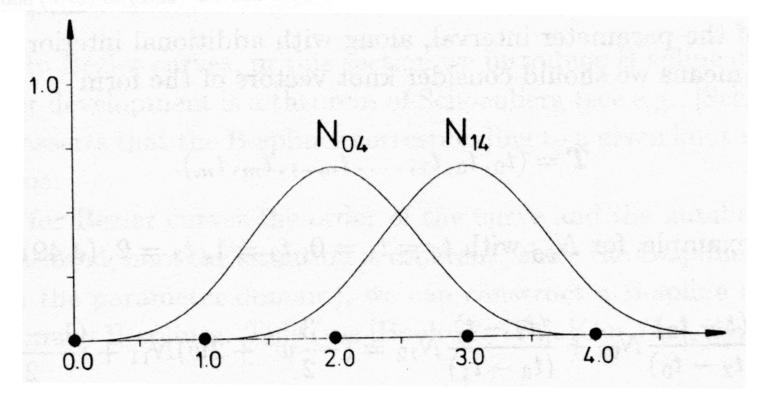


Fig. 4.22d. The B-splines  $N_{12}$ ,  $N_{22}$ .



**Fig. 4.22e.** The B-splines  $N_{03}$ ,  $N_{13}$ .



# Matrix form of Uniform Cubic B-Spline Blending Functions

$$M_{B} = \frac{1}{6} \begin{bmatrix} 1 & 3 & 1 \\ 3 & 6 & 3 & 0 \\ 6 & 3 & 0 \\ 4 & 1 & 0 \end{bmatrix}$$

# Closed B-Splines

Periodically extend the control points and the knots

$$P_{n+1} = P_0$$

$$t_{n+1} = t_0$$

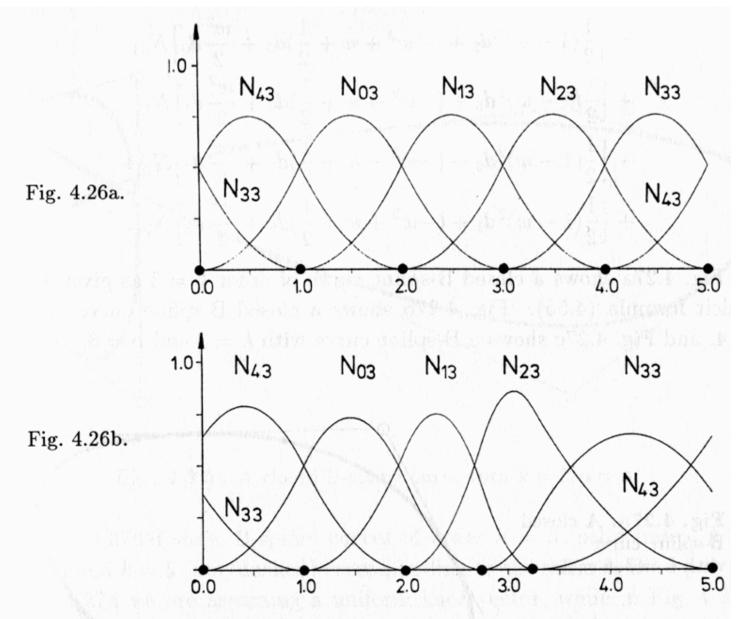
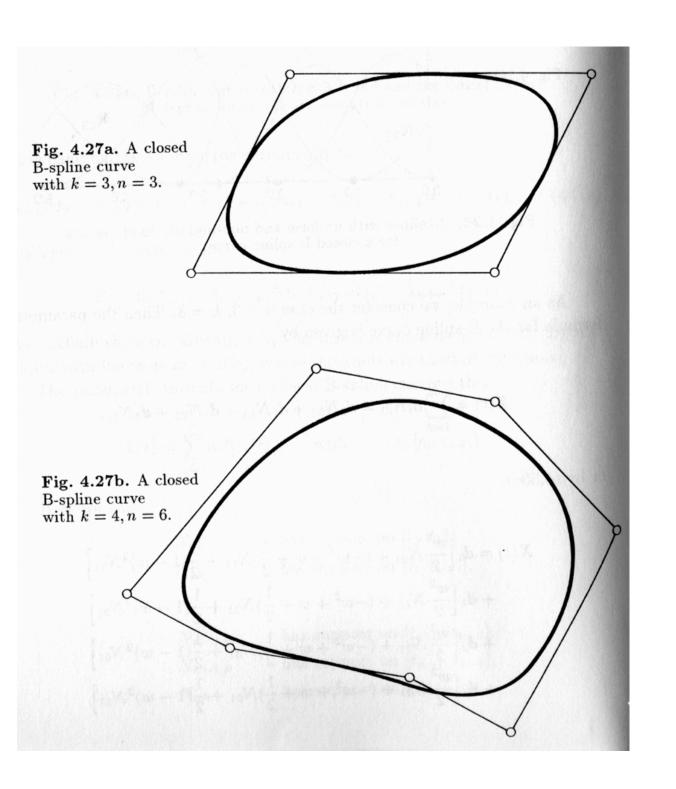


Fig. 4.26. B-splines with uniform and non-uniform knot vectors for a closed B-spline curve.



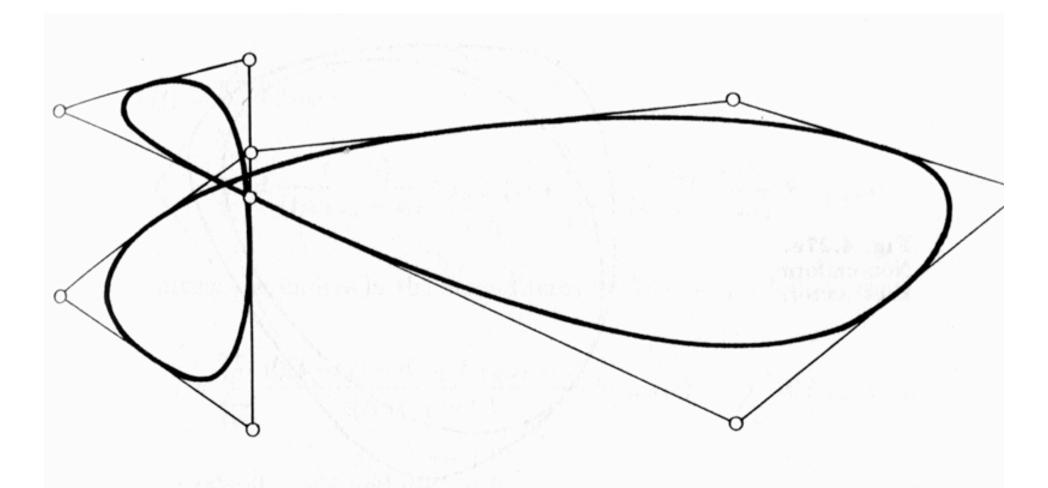
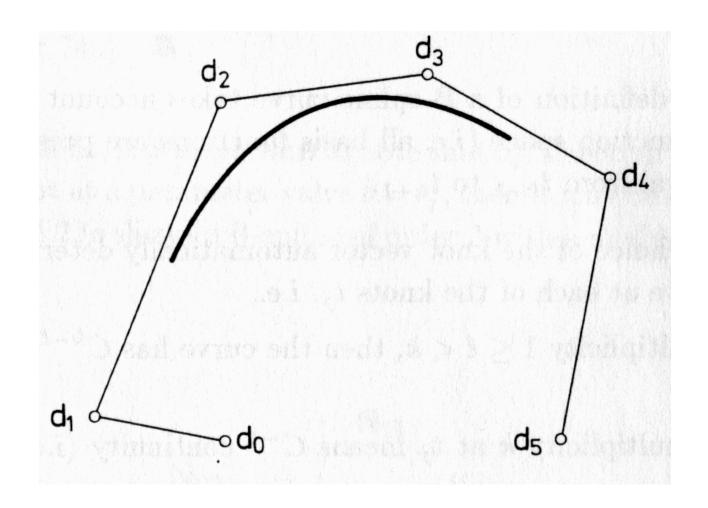


Fig. 4.27c. A closed B-spline curve with k = 3, n = 8.



Recall that each curve section is a blend of d control points.

What if we want to interpolate the endpoints?

#### Repeated knots

- Definition works for repeated knots (if we are understanding about 0/0)
- Repeated knot reduces continuity. A B-spline blending function has continuity C<sup>d-2</sup>; if the knot is repeated m times, continuity is now C<sup>d-m-1</sup>
- e.g. -> quadratic B-spline (i.e. order 3) with a double knot

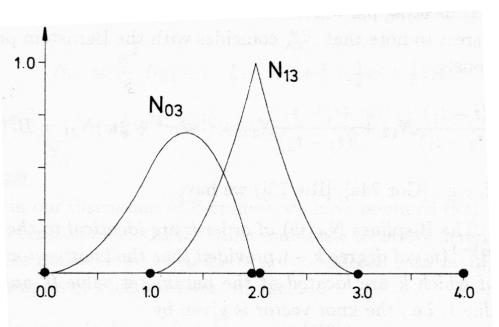


Fig. 4.22g. A quadratic B-spline with a double knot.

#### Most useful case

- Select the first d and the last d knots to be the same
  - we then get the first and last points lying on the curve
  - also, the curve is tangent to the first and last segment

- E.g. cubic case below
- Notice that a control point influences at most d parameter intervals **local control**

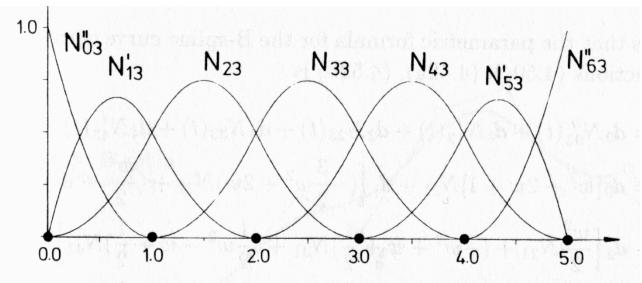
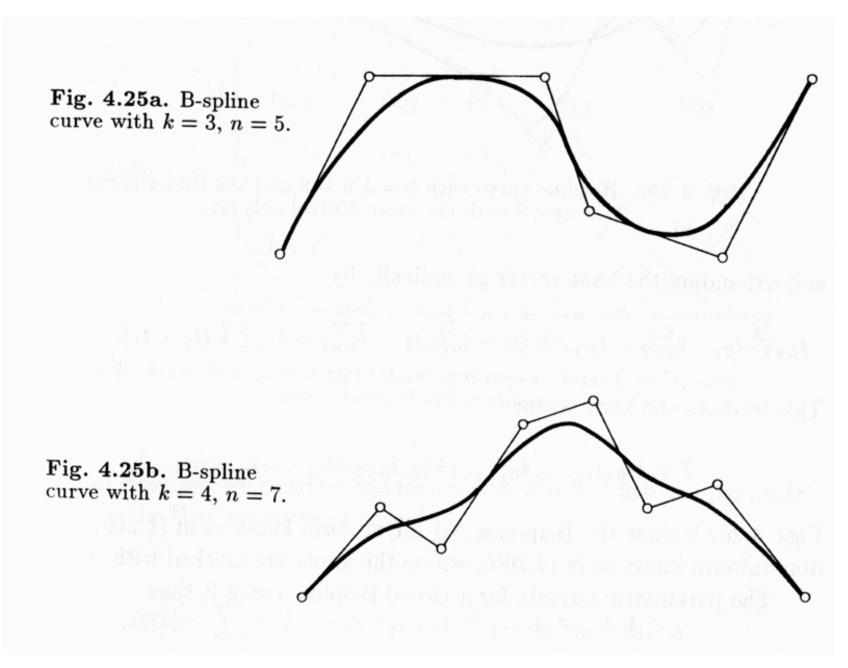


Fig. 4.24a. B-splines for an open B-spline curve with uniform knot vector.



k is our d - top curve has order 3, bottom order 4

Example of blending function with repeated knots at the endpoints and non-uniform spacing of interior knots

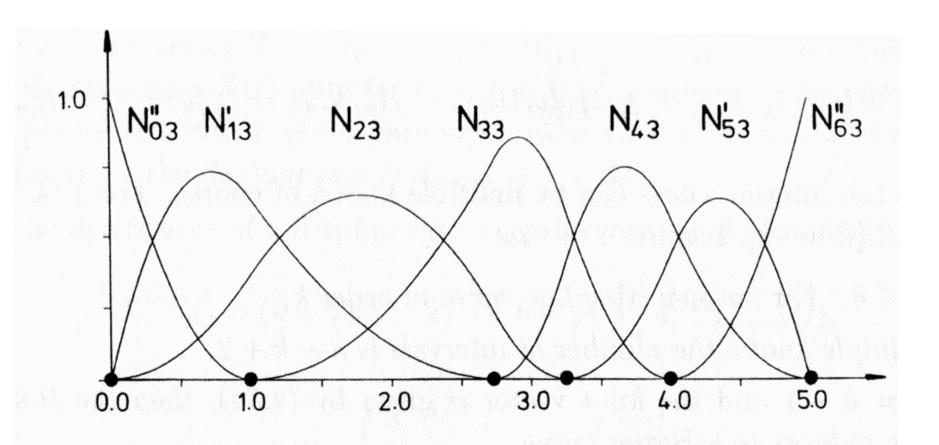


Fig. 4.24b. B-splines for an open B-spline curve with non-uniform knot vector.

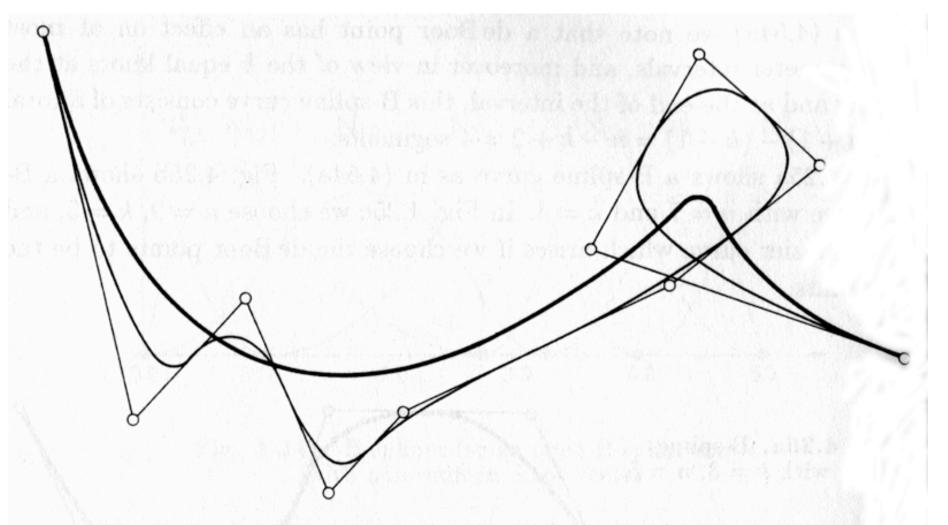


Fig. 4.25c. B-spline curve with k = 3, n = 9 and the Bézier curve of degree 9 with the same control polygon.

Bézier curve is the heavy curve

## **B-Spline** properties

- For a B-spline curve of order d
  - if m knots coincide, the curve is C<sup>d-m-1</sup> at the corresponding point
  - if d-1 consecutive\* points of the control polygon are collinear, then the curve is tangent to the polygon
  - if d consecutive\* points of the control polygon are collinear, then the curve and the polygon have a common segment
  - if d-1 points coincide, then the curve interpolates the common point and the two adjacent sides of the polygon are tangent to the curve
  - each segment of the curve lies in the convex hull of the associated d points

<sup>\*</sup>The fish shaped curve a few slides back have 4 collinear points (d=3), but they are not consecutive so the condition does not hold.