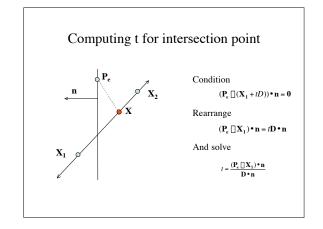
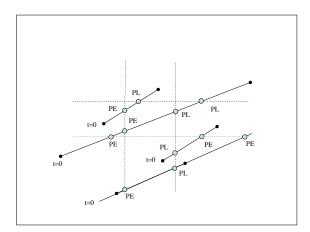
Clipping references

Hearn and Baker Foley at al. C-S (lines): p 317 C-S (lines): p 103 L-B (lines): p 322 L-B (lines): p 107 N-L (lines): p 325 N-L (lines): N.A. S-H (poly): p 331 S-H (poly): p 112 W-A(poly): p 335 W-A(poly): N.A.





Cyrus-Beck/Liang-Barsky--Algorithm

- Compute incoming (PE) t values, which are q_k/p_k for each $p_k < 0$
- Compute outgoing (PL) t values, which are q_k/p_k for each $p_k>0$
- Parameter value for small t end of the segment is:

t_{small}= max(0, incoming values)

• Parameter value for large t end of the segment is:

 t_{large} =min(1, outgoing values)

- If $t_{\text{small}} < t_{\text{large}}$, there is a segment portion in the clip window compute endpoints by substituting t values (otherwise reject as it is outside).

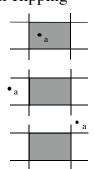
Cyrus-Beck/Liang-Barsky--Notes

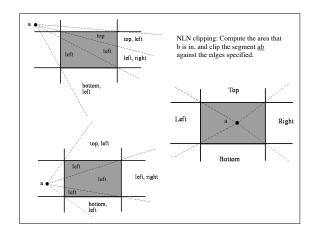
- · Works fine if clipping window is not an axis-aligned rectangle. Computing the t vaues is just more expensive.
- Bibliographic note: Original algorithm was Cyrus-Beck (close to what we have done here). A very similar algorithm was independently developed later by Liang-Barsky with some additional improvements for identifying early rejects as the t values are computed.

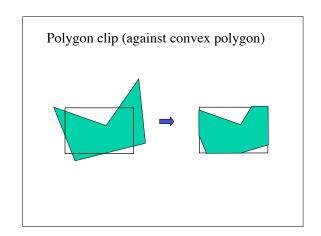
Nicholl-Lee-Nicholl clipping

- · Fast specialized method
- We will just outline the basic idea
- Consider segment with endpoints: a, b
- · Cases:
 - a inside
 - a in edge region
 - a in corner region
- For each case, we generate specialized test regions for b
- Which region b is in is determined by simple"which-side" tests.
- The region b is in determines which edges
- need to be clipped against.

 Speed is enhanced by good ordering of tests, and caching intermediate results

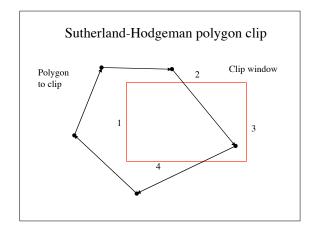


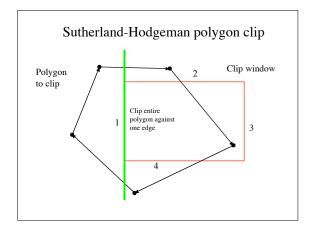


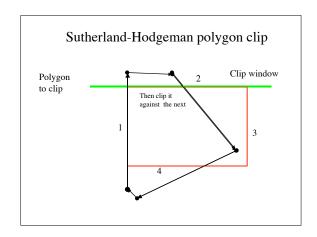


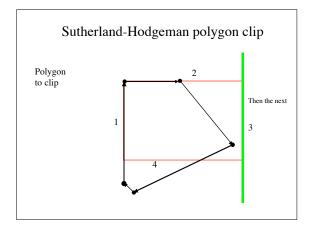
Sutherland-Hodgeman polygon clip

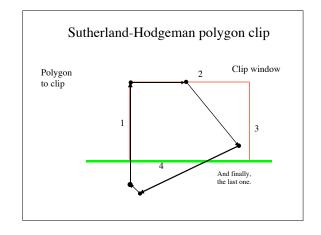
- Recall: polygon is convex if any line joining two points inside the polygon, also lies inside the polygon; implies that a point is inside if it is on the right side of each edge.
- Clipping each edge of a given polygon doesn't make sense how do we reassemble
 the pieces? We want to arrange doing so on the fly.
- Clipping the polygon against each edge of the clip window in *sequence* works if the clip window is *convex*.
- (Note similarity to Sutherland-Cohen line clipping)

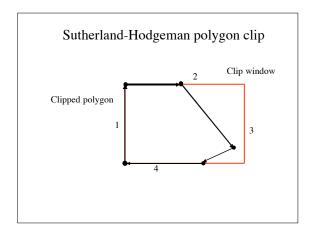












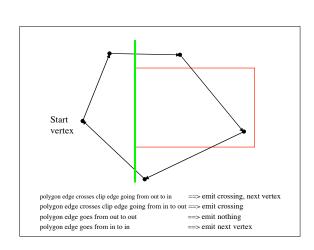
Clipping against current clip edge Polygon is a list of vertices • Four cases: polygon edge crosses clip edge going from out to in Think of process as rewriting polygon, vertex by vertex Check start vertex polygon edge crosses clip edge going from in to out - in - emit it out - ignore it Walk along vertices and for each edge consider four cases and apply corresponding action. polygon edge goes from out to out polygon edge goes from in to in

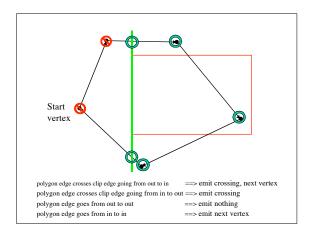
Clipping against current clip edge

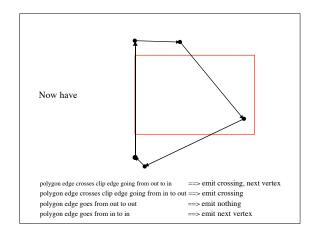
- Polygon is a list of vertices
- Think of process as rewriting polygon, vertex by vertex
- Check start vertex
 - in emit it
- out ignore it
- Walk along vertices and for each edge consider four cases and apply corresponding action.
- · Four cases:
 - polygon edge crosses clip edge going from out to in emit crossing, next vertex

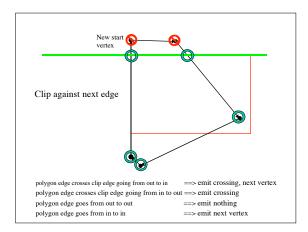
 - polygon edge crosses clip edge going from in to out emit crossing
 - polygon edge goes from out to out emit nothing

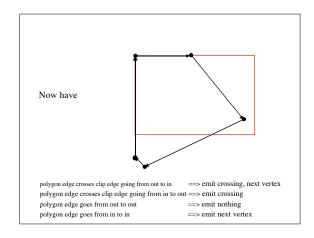
 - polygon edge goes from in to
 - · emit next vertex

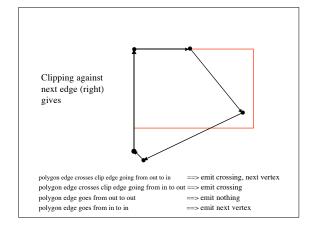


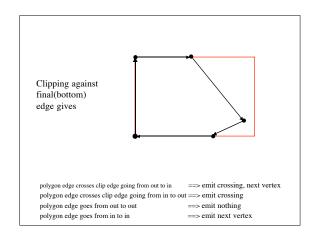






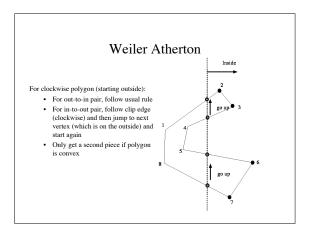






More Polygon clipping

- · Notice that we can have a pipeline of clipping processes, one against each edge, each operating on the output of the previous clipper -- substantial advantage.
- Unpleasantness can result from concave polygons; in particular, polygons with empty interior.
- Can modify algorithm for concave polygons (e.g. Weiler



Additional remarks on clipping

- Although everything discussed so far has been in terms of polygons/lines clipped against lines in 2D, all except Nicholl-Lee-Nicholl will work in 3D against convex regions without much change.
 This is because the central issue in each algorithm is the inside outside decision as a convex region is the intersection of half spaces.
- Inside-outside decisions can be made for lines in 2D, planes in 3D. e.g testing dx•n>=0
- Hence, all (except N-L-N) can be used to clip:
 - Lines against 3D convex regions (e.g. cubes)

 - Polygons against 3D convex regions (e.g. cubes)

 NLN could work in 3D, but the
- number of cases increases too much to be practical.