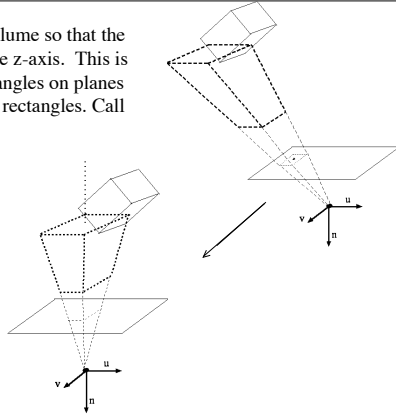


Step 2: Shear this volume so that the central axis lies on the z-axis. This is a shear, because rectangles on planes $z=\text{constant}$ must stay rectangles. Call this shear S_1



Shear S_1 takes previous window midpoint

$\begin{bmatrix} u_{\max} + u_{\min} \\ v_{\max} + v_{\min} \\ 0 \end{bmatrix}$ to $(0, 0, -f)$ - this means that matrix is

?

Shear S_1 takes previous window midpoint

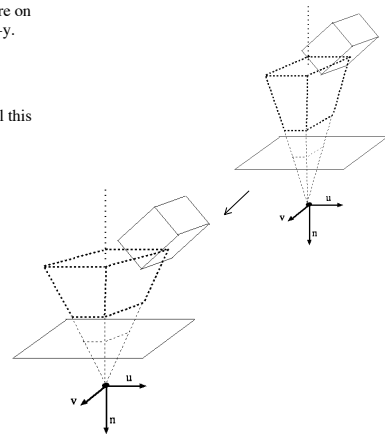
$\begin{bmatrix} u_{\max} + u_{\min} \\ v_{\max} + v_{\min} \\ 0 \end{bmatrix}$ to $(0, 0, -f)$ - this means that matrix is:

$$\begin{bmatrix} 0 & \frac{(u_{\min} + u_{\max})}{2f} & 0 \\ 0 & \frac{(v_{\min} + v_{\max})}{2f} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

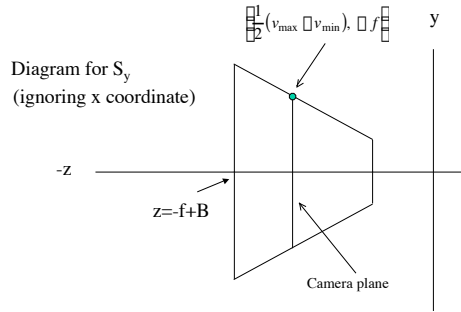
Note that the size of a rectangle in the image plane does not change.

3. Scale x, y so that planes are on $z=x$, $z=-x$ and $z=y$ and $z=-y$. Call this scale Sc_1

4. Isotropic scale so that far clipping plane is $z=-1$; call this scale Sc_2



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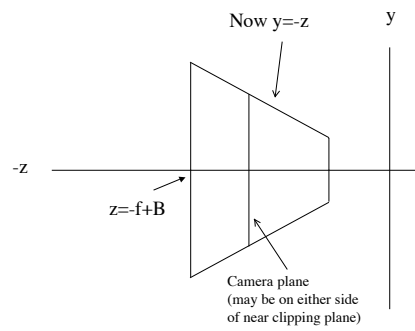
$$\frac{1}{2}(v_{\max} - v_{\min}), \frac{1}{2}f \rightarrow y = -z$$

$$k_y \frac{1}{2}(v_{\max} - v_{\min}) = f$$

$$k_y = \frac{2f}{(v_{\max} - v_{\min})} \quad (k_y \text{ is } y \text{ scale factor})$$

$$Sc_1 = \begin{bmatrix} \frac{2f}{(u_{\max} - u_{\min})} & 0 & 0 & 0 \\ 0 & \frac{2f}{(v_{\max} - v_{\min})} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

5. Now isotropic scale so that far
clipping plane is $z=-1$; call this
scale Sc_2



5. Now isotropic scale so that far clipping plane is $z=-1$; call this scale Sc_2

Currently, at far clipping plane, $z=-f+B$

Want a factor k so that $k(-f+B)=-1$

So, $k = -1 / (-f + B) = 1 / (f - B)$

(Note that B is negative, and k is positive)

$$Sc_2 = \begin{bmatrix} \frac{1}{f-B} & 0 & 0 & 0 \\ 0 & \frac{1}{f-B} & 0 & 0 \\ 0 & 0 & \frac{1}{f-B} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Note that the focal length, f , also gets transformed (needed for the perspective transformation coming up).

It is:

$$f' = \frac{f}{f-B}$$

3D Viewing Pipeline

$$\begin{pmatrix} \text{Point in} \\ \text{canonical} \\ \text{camera} \\ \text{coordinates} \end{pmatrix} Sc_2 Sc_1 S_1 T_2 R_1 T_1 \begin{pmatrix} \text{Point in} \\ \text{world} \\ \text{coordinates} \end{pmatrix}$$
