

Plan A: Clipping against the canonical frustum

2D algorithms are easily extended. For line clipping with Cohen Sutherland we use the following 6 out codes:

$$y > z \quad y < z \quad x > z \quad x < z \quad z < -1 \quad z > z_{\min}$$

$$(z_{\min} = (f - F) / (B - f))$$

Recall C.S.
for segments

Compute out codes for endpoints
While not trivial accept and not trivial reject:
Clip against a problem edge (one point in, one out)
Compute out codes again
Return appropriate data structure

Clipping against the canonical frustum

Clipping polygons in 3D against canonical frustum planes is simpler and more efficient than the general case.

Recall the S.H. gives four cases:

- Polygon edge crosses clip **plane** going from out to in
 - emit crossing, next vertex
- Polygon edge crosses clip **plane** going from in to out
 - emit crossing
- Polygon edge goes from out to out
 - emit nothing
- Polygon edge goes from in to in
 - emit next vertex

(The above is from before, just change “edge” to “plane”)

Object in world coordinates
(after modeling transforms)

Transform object from world
coordinates to standard camera
coordinates ✓

Clip against canonical
view frustum

Project using standard
camera model ✓

Plan A: Clip against
canonical frustum ✓
(relatively easy—we chose
the canonical frustum so
that it would be easy!)

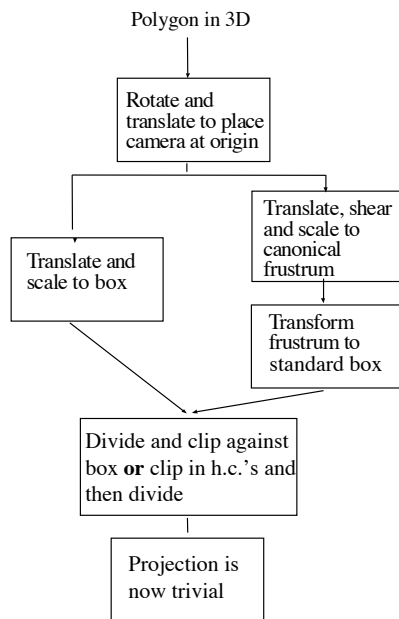
Plan B: Be even more
clever. Further transform to
cube and clip in
homogenous coordinates.

Plan B: Clipping in homogenous coords

- For any camera, can turn the view frustum into a regular parallelepiped (box). We will use the box bounded by $x = \pm 1$, $y = \pm 1$, $z = -1$, and $z = 0$.
- Advantages
 - Simplified clipping in homogenous coordinates
 - Extends to cases where we use homogenous coordinates to represent additional information (and w could be negative).
 - Can simplify visibility algorithms.
- Approach: clever use of homogenous coordinates

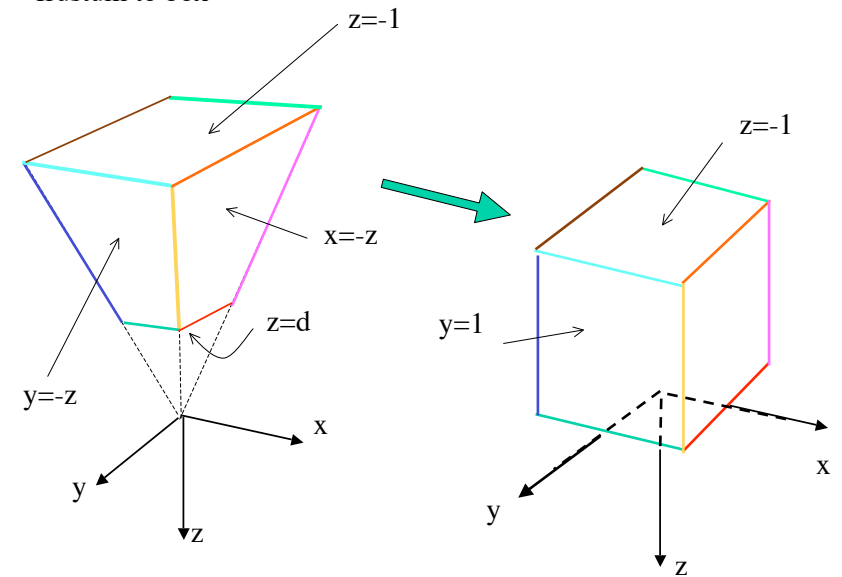
Plan B

Orthographic case

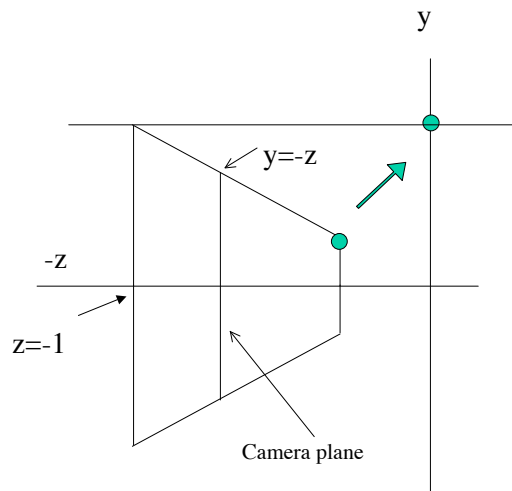


Perspective case

Transforming canonical frustum to box

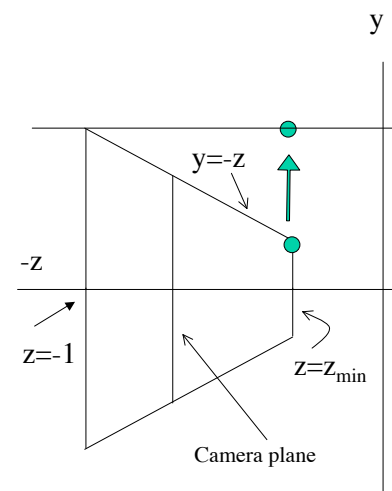


Transforming canonical frustum to box



Do this in two steps. One stretch in y (and x), and one stretch in z .

Transforming canonical frustum to box

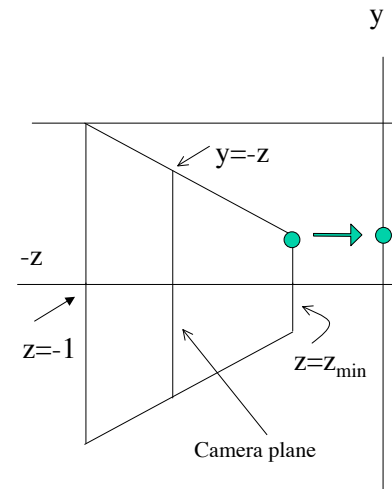


The picture should suggest an appropriate scaling for y .

It is ?

A diagram illustrating a camera plane in a 2D coordinate system. The vertical axis is labeled y and the horizontal axis is labeled $-z$. A trapezoidal region represents the camera plane, with its left boundary at $-z = -1$ and its right boundary at $-z = z_{\min}$. The top edge of the plane is labeled $y = -z$. Two green dots are placed on the right boundary at different heights, with a green arrow pointing upwards between them, indicating a vertical displacement. A label "Camera plane" with an arrow points to the trapezoidal region.

Transformation is **non-linear**, but
in h.c., we can make $w = (-z)$.



(Thus in our box, depth transforms **non-linearly**)

?

So, the matrix is

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{1}{1+z_{\min}} & \frac{-z_{\min}}{1+z_{\min}} \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

Mapping to standard view volume (additional comments)

- The mapping from $[z_{\min}, -1]$ to $[0, -1]$ is non-linear. (Of course, there exists a linear mapping, but not if we want everything else to work out nicely in h.c.).
- So a change in depth of ΔD at the near plane maps to a larger depth difference in screen coordinates than the same ΔD at the far plane.
- But order is preserved (important!); the function is monotonic (proof?).
- And lines are still lines (proof?) and planes are still planes (important!).

Transforming canonical
frustum to box

