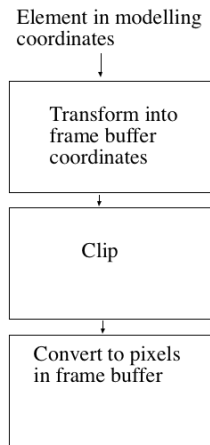


## Clipping

- 2D elements are laid out in a convenient (often user based) coordinate system--perhaps km for a map--and then transformed to a frame buffer coordinate system.
- Objects that are to be drawn must lie inside frame buffer, and may have to lie inside particular region - e.g. viewport.
- We want to dodge additional expensive operations on objects or parts of objects that won't be displayed.
- How do we ensure line/polygon lies inside a region?

### Clipping in the 2D pipeline



## Clipping references

### Hearn and Baker

C-S (lines): p 317  
L-B (lines): p 322  
N-L (lines): p 325

S-H (poly): p 331  
W-A(poly): p 335

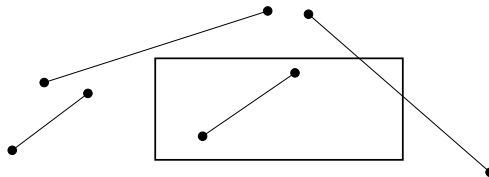
### Foley at al.

C-S (lines): p 103  
L-B (lines): p 107  
N-L (lines): N.A.

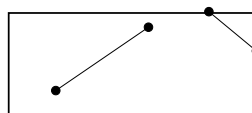
S-H (poly): p 112  
W-A(poly): N.A.

## Clipping lines

Have

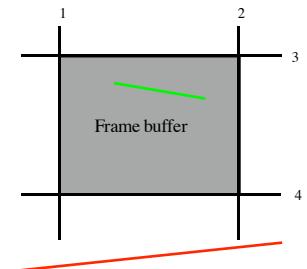


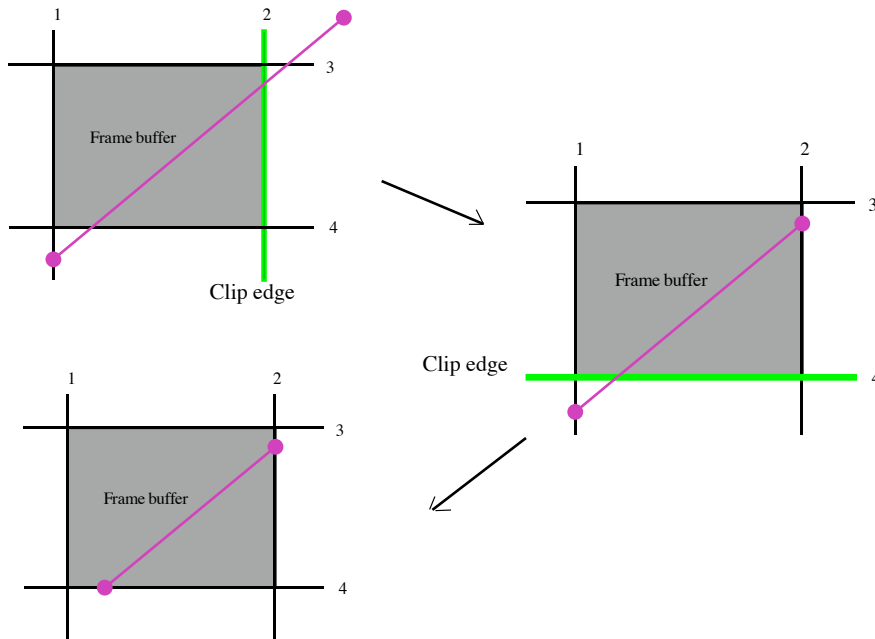
Need



## Cohen-Sutherland clipping (lines)

- Clip line against convex region.
- For **each** edge of the region, clip line against that edge:
  - line all on wrong side of any edge? throw it away (**trivial reject**--e.g. red line with respect to bottom edge)
  - line all on correct side of *all* edges? doesn't need clipping (trivial accept--e.g. green line).
  - line crosses edge? **replace** endpoint on wrong side with crossing point (**clip**)

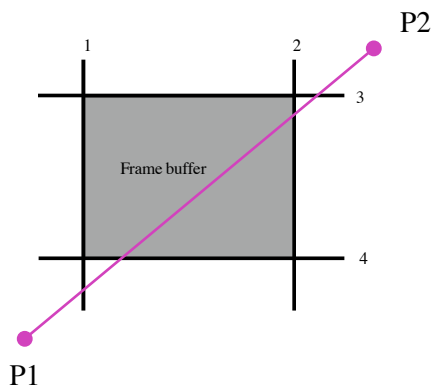




## Cohen Sutherland - details

- Only need to clip line against edges where one endpoint is inside and one is outside.
- The state of the *outside* endpoint (e.g., in or out, w.r.t a given edge) changes due to clipping as we proceed--need to track this.
- Use “outcode” to record endpoint in/out wrt each edge. One bit per clipping edge, 1 if out, 0 if in.

## Outcode example



Outcode for P1?

Outcode for P2?

## Cohen Sutherland - details

- Trivial reject condition?
- Trivial accept condition?
- Clipping line against vertical/horizontal edge is easy:
  - line has endpoints  $(x_s, y_s)$  and  $(x_e, y_e)$
  - e.g. (vertical case) clip against  $x=a$  gives the point?
  - new point replaces the point for which outcode() is true
- Algorithm is valid for any convex clipping region (intersections are slightly more difficult)

## Cohen Sutherland - Algorithm

- Compute outcodes for endpoints
- While not trivial accept and not trivial reject:
  - clip against a problem edge (i.e. one for which an outcode bit is 1)
  - compute outcodes again
- Return appropriate data structure

## Cyrus-Beck/Liang-Barsky clipping

- Parametric clipping: consider line in parametric form and reason about the parameter values
- More efficient, as we don't compute the coordinate values at irrelevant vertices

- Line is:

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} + t \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix}$$

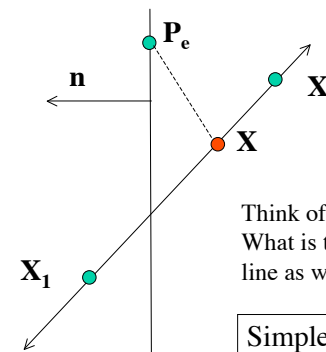
$$\Delta x = x_2 - x_1$$

$$\Delta y = y_2 - y_1$$

## Cyrus-Beck/Liang-Barsky clipping

- Consider the parameter values,  $t$ , for each clip edge
- Only  $t$  inside  $(0,1)$  is relevant
- Assumptions
  - $\mathbf{X}_1 \neq \mathbf{X}_2$
  - Ignore case where line is parallel to a clip edge (has no effect, but would lead to divide by zero).
  - We have a normal,  $\mathbf{n}$ , for each clip edge pointing outward
  - For axis aligned rectangle (the usual case) these are?

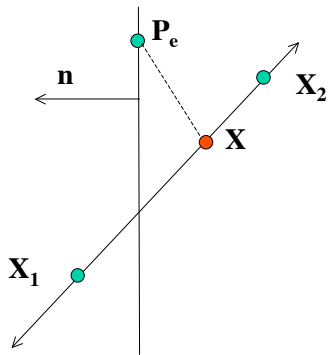
### Computing $t$ for intersection point



Think of  $X$  moving along the line shown. What is the condition that it is on the other line as well (i.e., intersects?)

Simplest to work from condition  $(\mathbf{X}(t) - \mathbf{P}_e) \cdot \mathbf{n} = 0$

### Computing t for intersection point



Set

$$\mathbf{D} = \mathbf{X}_2 - \mathbf{X}_1$$

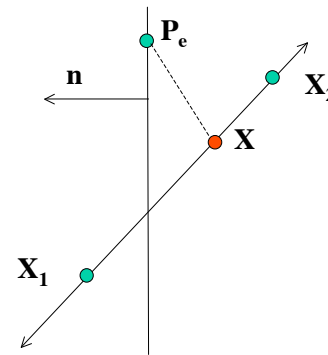
Then

$$\mathbf{X} = \mathbf{X}_1 + t\mathbf{D}$$

And condition is

$$(\mathbf{P}_e - (\mathbf{X}_1 + t\mathbf{D})) \cdot \mathbf{n} = 0$$

### Computing t for intersection point, X



Condition

$$(\mathbf{P}_e - (\mathbf{X}_1 + t\mathbf{D})) \cdot \mathbf{n} = 0$$

Rearrange

$$(\mathbf{P}_e - \mathbf{X}_1) \cdot \mathbf{n} = t\mathbf{D} \cdot \mathbf{n}$$

And solve

$$t = \frac{(\mathbf{P}_e - \mathbf{X}_1) \cdot \mathbf{n}}{\mathbf{D} \cdot \mathbf{n}}$$

### Computing t for intersection point

From previous slide  $t = \frac{(\mathbf{P}_e - \mathbf{X}_1) \cdot \mathbf{n}}{\mathbf{D} \cdot \mathbf{n}}$

This simplifies greatly for axis aligned rectangles

Consider left edge. Now  $\mathbf{n}=?$  and  $\mathbf{P}_e=?$

And  $t = ?$

- All four special cases can expressed by:  $t = \frac{q_k}{p_k}$

- Where

$$p_1 = -\Delta x \quad q_1 = x_1 - x_{\min}$$

$$p_2 = \Delta x \quad q_2 = x_{\max} - x_1$$

$$p_3 = -\Delta y \quad q_3 = y_1 - y_{\min}$$

$$p_4 = \Delta y \quad q_4 = y_{\max} - y_1$$

- Faster derivation for this special case?

- All four cases can be expressed by:  $t = \frac{q_k}{p_k}$

- Where

$$p_1 = -\Delta x \quad q_1 = x_1 - x_{\min}$$

$$p_2 = \Delta x \quad q_2 = x_{\max} - x_1$$

$$p_3 = -\Delta y \quad q_3 = y_1 - y_{\min}$$

$$p_4 = \Delta y \quad q_4 = y_{\max} - y_1$$

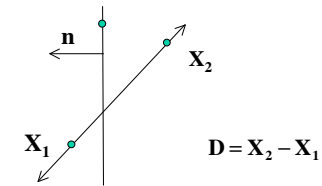
- One can also get this special case **directly** by solving:

$$x_{\min} \leq x_1 + t\Delta x \leq x_{\max}$$

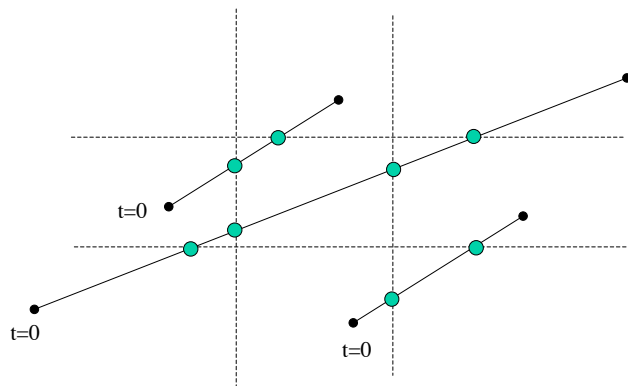
$$y_{\min} \leq y_1 + t\Delta y \leq y_{\max}$$

## Cyrus-Beck/Liang-Barsky (cont)

- Next step: Use the  $t$ 's to determine the clip points
- Recall that only  $t$  in  $(0,1)$  is relevant, but we need additional logic to determine clip endpoints from multiple  $t$ 's inside  $(0,1)$ .
- We imagine going from  $X_1$  to  $X_2$  and classify intersections as either potentially entering (PE) or potentially leaving (PL) if they go across a clip edge **from outside in or inside out**.
- This** is easily determined from the sign of  $\mathbf{D} \cdot \mathbf{n}$  which we have already computed.



PE vs PL example



## Cyrus-Beck/Liang-Barsky--Algorithm

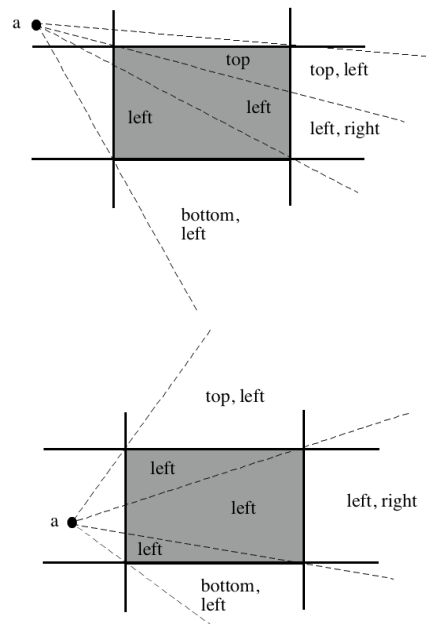
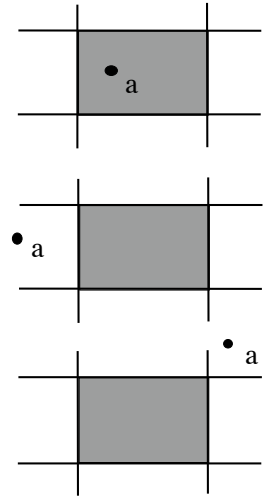
- Compute incoming (PE)  $t$  values, which are  $q_k/p_k$  for each  $p_k < 0$
- Compute outgoing (PL)  $t$  values, which are  $q_k/p_k$  for each  $p_k > 0$
- Parameter value for small  $t$  end of the segment is:
 
$$t_{\text{small}} = \max(0, \text{incoming values})$$
- Parameter value for large  $t$  end of the segment is:
 
$$t_{\text{large}} = \min(1, \text{outgoing values})$$
- If  $t_{\text{small}} < t_{\text{large}}$ , there is a segment portion in the clip window - compute endpoints by substituting these two  $t$  values (how)?
- Otherwise reject because it is outside.

## Cyrus-Beck/Liang-Barsky--Notes

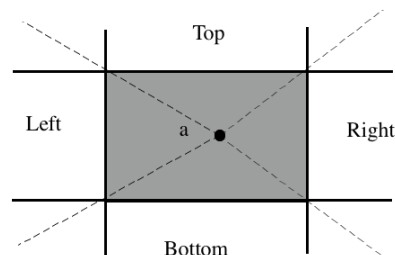
- Works fine if clipping window is not an axis-aligned rectangle. Computing the  $t$  values is just more expensive.
- **Bibliographic note:** Original algorithm was Cyrus-Beck (close to what we have done here). A very similar algorithm was independently developed later by Liang-Barsky with some additional improvements for identifying early rejects as the  $t$  values are computed.

## Nicholl-Lee-Nicholl clipping

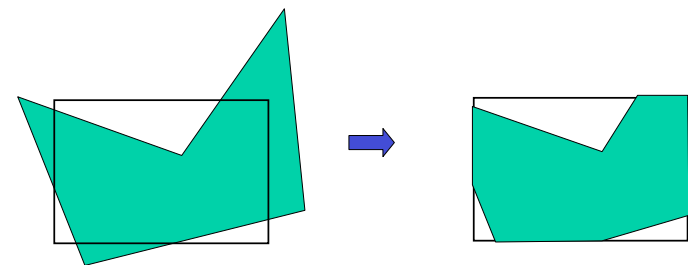
- Fast specialized method
- We will just outline the basic idea
- Consider segment with endpoints:  $a$ ,  $b$
- Cases:
  - $a$  inside
  - $a$  in edge region
  - $a$  in corner region
- For each case, we generate specialized test regions for  $b$
- Which region  $b$  is in is determined by simple “which-side” tests.
- The region  $b$  is in determines which edges need to be clipped against.
- Speed is enhanced by good ordering of tests, and caching intermediate results



NLN clipping: Compute the area that  $b$  is in, and clip the segment  $ab$  against the edges specified.



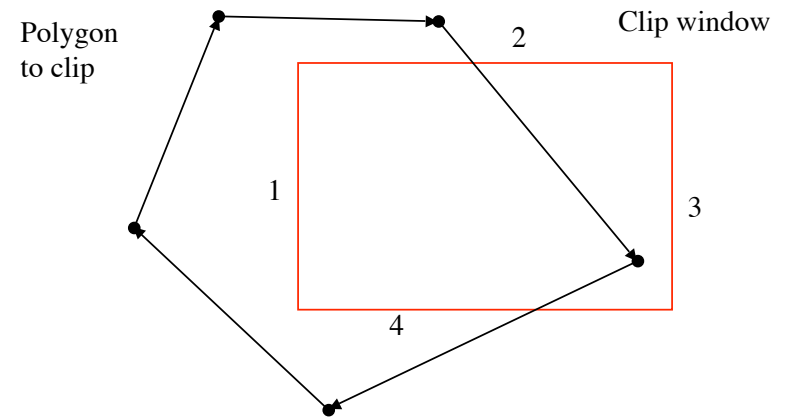
## Polygon clip (against convex polygon)



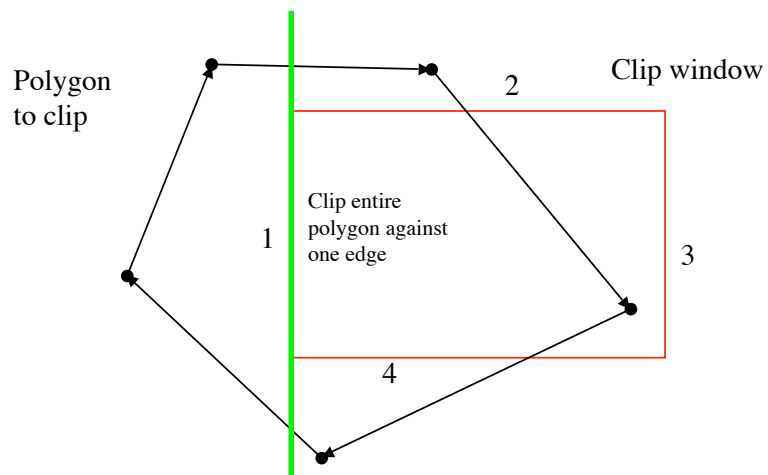
## Sutherland-Hodgeman polygon clip

- Recall: polygon is convex if any line joining two points inside the polygon, also lies inside the polygon; implies that a point is inside if it is on the right side of each edge.
- Clipping each edge of a given polygon doesn't make sense - how do we reassemble the pieces? We want to arrange doing so on the fly.
- Clipping the polygon against each edge of the clip window in *sequence* works if the clip window is *convex*.
- (Note similarity to Sutherland-Cohen line clipping)

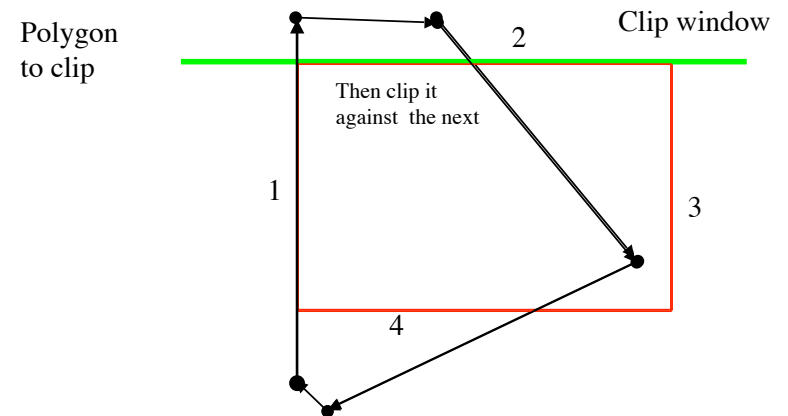
## Sutherland-Hodgeman polygon clip



## Sutherland-Hodgeman polygon clip

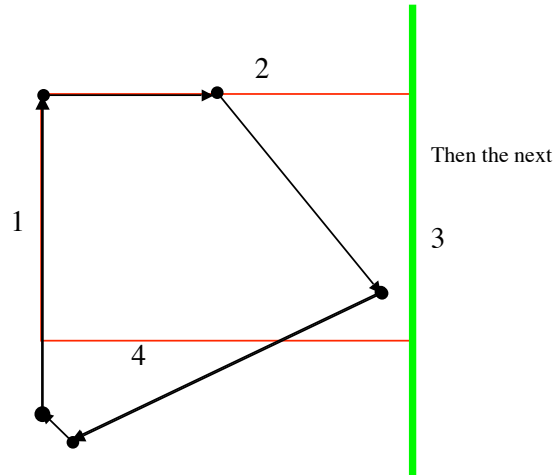


## Sutherland-Hodgeman polygon clip



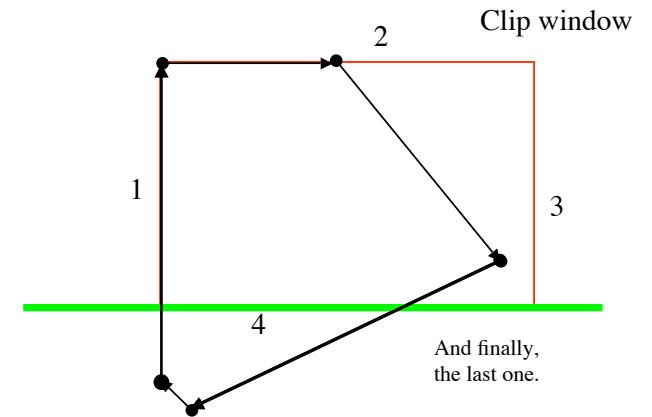
## Sutherland-Hodgeman polygon clip

Polygon  
to clip



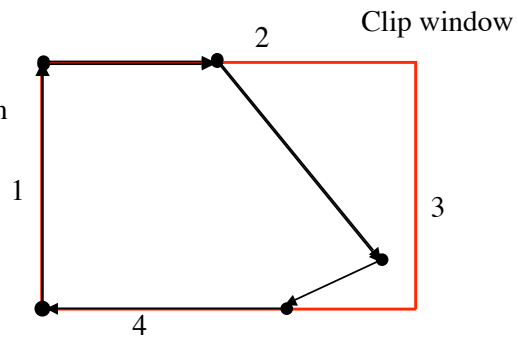
## Sutherland-Hodgeman polygon clip

Polygon  
to clip



## Sutherland-Hodgeman polygon clip

Clipped polygon

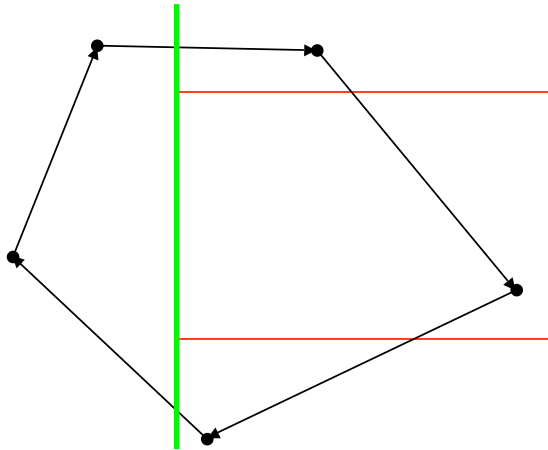


## Clipping against current clip edge

- Polygon is a list of vertices
- Think of process as rewriting polygon, vertex by vertex
- Check start vertex
  - in - emit it
  - out - ignore it
- Walk along vertices and for each edge consider four cases and apply corresponding action.
  - Four cases:
    - polygon edge crosses clip edge going from out to in
      -
    - polygon edge crosses clip edge going from in to out
      -
    - polygon edge goes from out to out
      -
    - polygon edge goes from in to in
      -

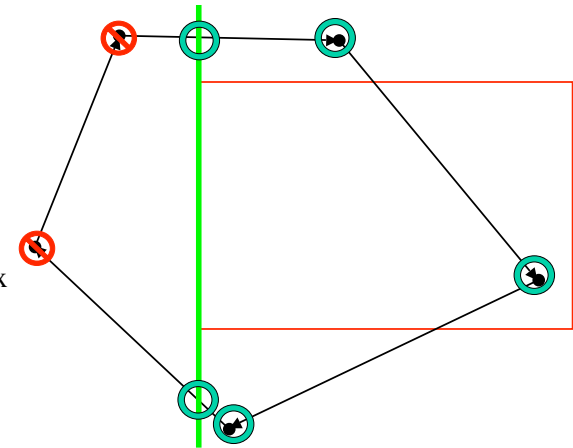


Start  
vertex



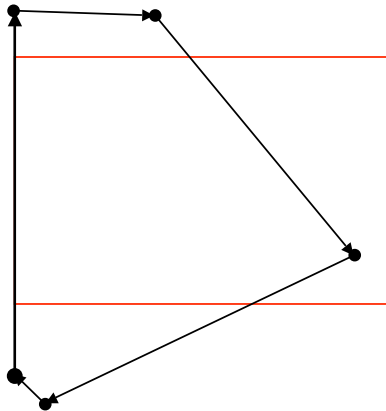
polygon edge crosses clip edge going from out to in ==> emit crossing, next vertex  
 polygon edge crosses clip edge going from in to out ==> emit crossing  
 polygon edge goes from out to out ==> emit nothing  
 polygon edge goes from in to in ==> emit next vertex

Start  
vertex



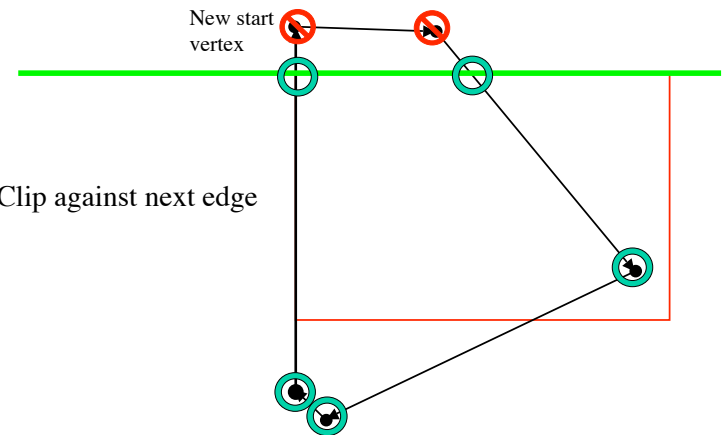
polygon edge crosses clip edge going from out to in ==> emit crossing, next vertex  
 polygon edge crosses clip edge going from in to out ==> emit crossing  
 polygon edge goes from out to out ==> emit nothing  
 polygon edge goes from in to in ==> emit next vertex

Now have



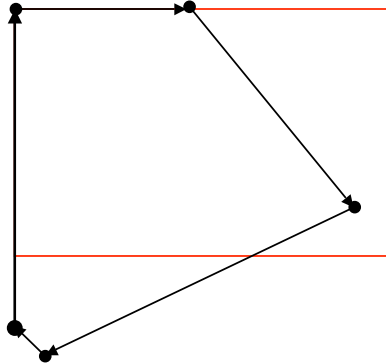
polygon edge crosses clip edge going from out to in ==> emit crossing, next vertex  
 polygon edge crosses clip edge going from in to out ==> emit crossing  
 polygon edge goes from out to out ==> emit nothing  
 polygon edge goes from in to in ==> emit next vertex

Clip against next edge



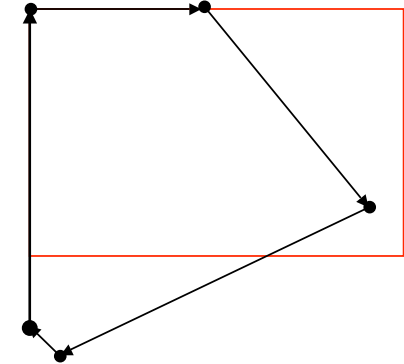
polygon edge crosses clip edge going from out to in ==> emit crossing, next vertex  
 polygon edge crosses clip edge going from in to out ==> emit crossing  
 polygon edge goes from out to out ==> emit nothing  
 polygon edge goes from in to in ==> emit next vertex

Now have



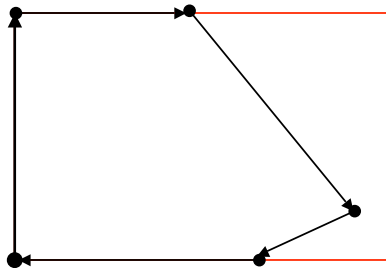
polygon edge crosses clip edge going from out to in ==> emit crossing, next vertex  
 polygon edge crosses clip edge going from in to out ==> emit crossing  
 polygon edge goes from out to out ==> emit nothing  
 polygon edge goes from in to in ==> emit next vertex

Clipping against  
next edge (right)  
gives



polygon edge crosses clip edge going from out to in ==> emit crossing, next vertex  
 polygon edge crosses clip edge going from in to out ==> emit crossing  
 polygon edge goes from out to out ==> emit nothing  
 polygon edge goes from in to in ==> emit next vertex

Clipping against  
final(bottom)  
edge gives



polygon edge crosses clip edge going from out to in ==> emit crossing, next vertex  
 polygon edge crosses clip edge going from in to out ==> emit crossing  
 polygon edge goes from out to out ==> emit nothing  
 polygon edge goes from in to in ==> emit next vertex

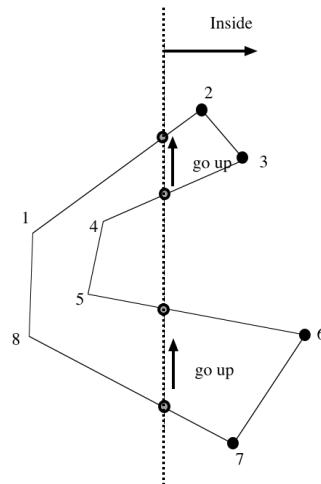
## More Polygon clipping

- Notice that we can have a pipeline of clipping processes, one against each edge, each operating on the output of the previous clipper -- substantial advantage.
- Unpleasantness can result from concave polygons; in particular, polygons with empty interior.
- Can modify algorithm for concave polygons (e.g. Weiler Atherton)

## Weiler Atherton

For clockwise polygon (starting outside):

- For out-to-in pair, follow usual rule
- For in-to-out pair, follow clip edge (clockwise) and then jump to next vertex (which is on the outside) and start again
- Only get a second piece if polygon is convex



## Additional remarks on clipping

- Although everything discussed so far has been in terms of polygons/lines clipped against lines in 2D, all - except Nicholl-Lee-Nicholl - will work in 3D against convex regions without much change.
- This is because the central issue in each algorithm is the inside outside decision as a convex region is the intersection of half spaces.
- Inside-outside decisions can be made for lines in 2D, planes in 3D. e.g testing  $dx \cdot n \geq 0$
- Hence, all (except N-L-N) can be used to clip:
  - Lines against 3D convex regions (e.g. cubes)
  - Polygons against 3D convex regions (e.g. cubes)
- NLN could work in 3D, but the number of cases increases too much to be practical.