

Cyrus-Beck/Liang-Barsky clipping

- Parametric clipping: consider line in parametric form and reason about the parameter values
 - More efficient, as we don't compute the coordinate values at irrelevant vertices
- Line is:

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} + t \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix}$$

$$\Delta x = x_2 - x_1$$

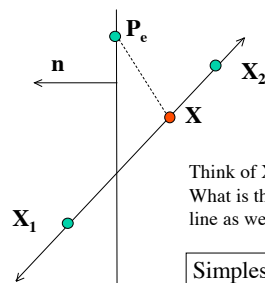
$$\Delta y = y_2 - y_1$$
 - Segment restricts t to be inside $[0,1]$

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Cyrus-Beck/Liang-Barsky clipping

- Consider the parameter values, t , for each clip edge
- Only t inside $(0,1)$ is relevant
- Assumptions
 - $\mathbf{X}_1 \neq \mathbf{X}_2$
 - Ignore case where line is parallel to a clip edge (has no effect, but would lead to divide by zero).
 - We have a normal, \mathbf{n} , for each clip edge pointing outward
 - For axis aligned rectangle (the usual case) these are:
left $(-1,0)$ right $(1,0)$ top $(0,1)$ bottom $(0,-1)$

Computing t for intersection point

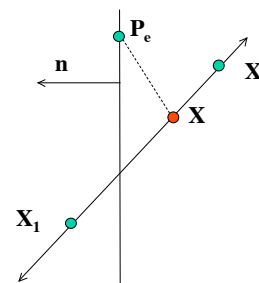


Think of X moving along the line shown. What is the condition that it is on the other line as well (i.e., intersects?)

Simplest to work from condition $(\mathbf{P}_e - \mathbf{X}(t)) \cdot \mathbf{n} = 0$

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Computing t for intersection point



Set

$$\mathbf{D} = \mathbf{X}_2 - \mathbf{X}_1$$

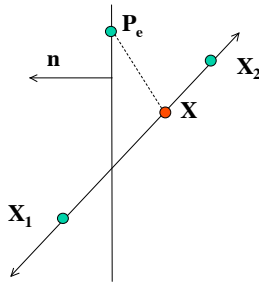
Then

$$\mathbf{X}(t) = \mathbf{X}_1 + t\mathbf{D}$$

And condition is

$$(\mathbf{P}_e - (\mathbf{X}_1 + t\mathbf{D})) \cdot \mathbf{n} = 0$$

Computing t for intersection point



Condition

$$(\mathbf{P}_e - (\mathbf{X}_1 + t\mathbf{D})) \cdot \mathbf{n} = 0$$

Rearrange

$$(\mathbf{P}_e - \mathbf{X}_1) \cdot \mathbf{n} = t\mathbf{D} \cdot \mathbf{n}$$

And solve

$$t = \frac{(\mathbf{P}_e - \mathbf{X}_1) \cdot \mathbf{n}}{\mathbf{D} \cdot \mathbf{n}}$$

Computing t for intersection point

From previous slide $t = \frac{(\mathbf{P}_e - \mathbf{X}_1) \cdot \mathbf{n}}{\mathbf{D} \cdot \mathbf{n}}$

This simplifies greatly for axis aligned rectangles

Consider left edge. Now $\mathbf{n}=?$ and $\mathbf{P}_e=?$

And $t = ?$

Computing t for intersection point

From previous slide $t = \frac{(\mathbf{P}_e - \mathbf{X}_1) \cdot \mathbf{n}}{\mathbf{D} \cdot \mathbf{n}}$

This simplifies greatly for axis aligned rectangles

Consider left edge. Now $\mathbf{n}=(-1,0)$ and $\mathbf{P}_e=(x_{\min},0)$

And $t = \frac{(x_{\min} - x_1)}{\Delta x}$

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- All four special cases can expressed by: $t = \frac{q_k}{p_k}$

- Where

$$p_1 = -\Delta x \quad q_1 = x_1 - x_{\min}$$

$$p_2 = \Delta x \quad q_2 = x_{\max} - x_1$$

$$p_3 = -\Delta y \quad q_3 = y_1 - y_{\min}$$

$$p_4 = \Delta y \quad q_4 = y_{\max} - y_1$$

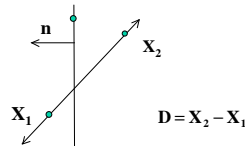
- One can also get this special case **directly** by solving:

$$x_{\min} \leq x_1 + t\Delta x \leq x_{\max}$$

$$y_{\min} \leq y_1 + t\Delta y \leq y_{\max}$$

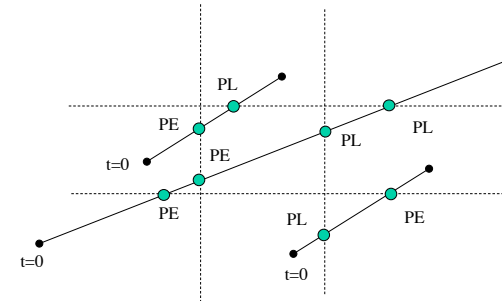
Cyrus-Beck/Liang-Barsky (cont)

- Next step: Use the t 's to determine the clip points
- Recall that only t in $(0,1)$ is relevant, but we need additional logic to determine clip endpoints from multiple t 's inside $(0,1)$.
- We imagine going from X_1 to X_2 and classify intersections as either potentially entering (PE) or potentially leaving (PL) if they go across a clip edge **from outside in or inside out**.
- This is easily determined from the sign of $\mathbf{D} \cdot \mathbf{n}$ which we have already computed.



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PE vs PL example



Cyrus-Beck/Liang-Barsky--Algorithm

- Compute incoming (PE) t values, which are q_k/p_k for each $p_k < 0$
- Compute outgoing (PL) t values, which are q_k/p_k for each $p_k > 0$
- Parameter value for small t end of the segment is:

$$t_{\text{small}} = \max(0, \text{incoming values})$$
- Parameter value for large t end of the segment is:

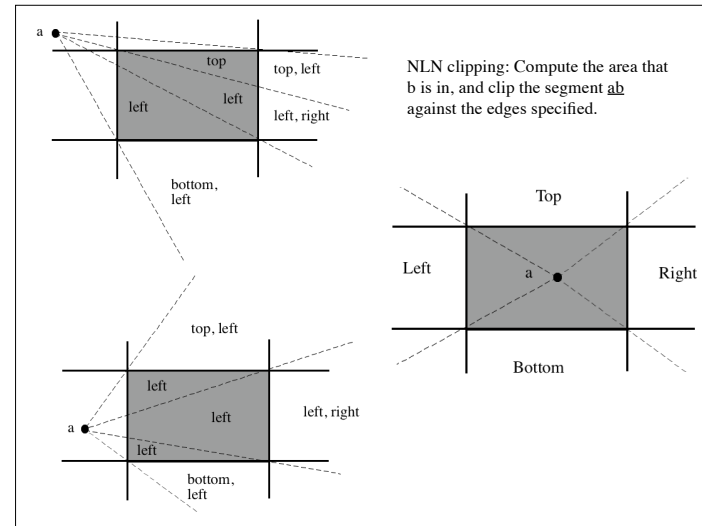
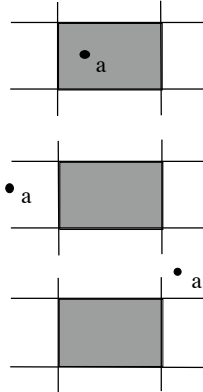
$$t_{\text{large}} = \min(1, \text{outgoing values})$$
- If $t_{\text{small}} < t_{\text{large}}$, there is a segment portion in the clip window - compute endpoints by substituting these two t values (how)?
- Otherwise reject because it is outside.

Cyrus-Beck/Liang-Barsky--Notes

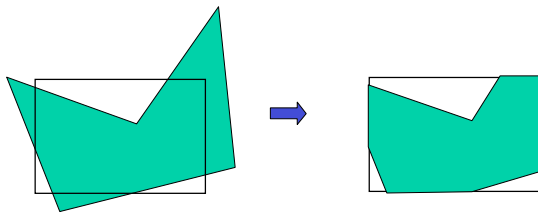
- Works fine if clipping window is not an axis-aligned rectangle. Computing the t values is just more expensive.
- **Bibliographic note:** Original algorithm was Cyrus-Beck (close to what we have done here). A very similar algorithm was independently developed later by Liang-Barsky with some additional improvements for identifying early rejects as the t values are computed.

Nicholl-Lee-Nicholl clipping

- Fast specialized method
- We will just outline the basic idea
- Consider segment with endpoints: a , b
- Cases:
 - a inside
 - a in edge region
 - a in corner region
- For each case, we generate specialized test regions for b
- Which region b is in is determined by simple "which-side" tests.
- The region b is in determines which edges need to be clipped against.
- Speed is enhanced by good ordering of tests, and caching intermediate results



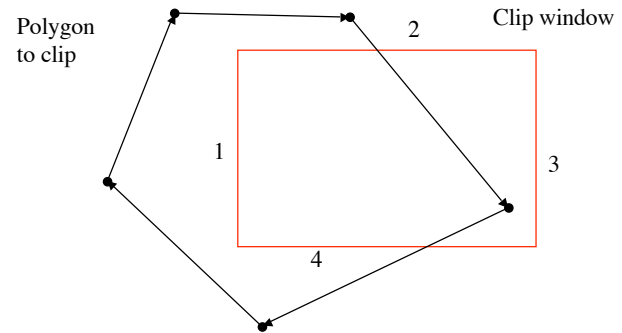
Polygon clip (against convex polygon)



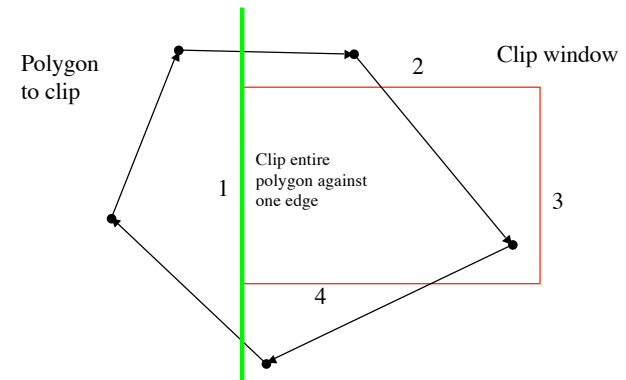
Sutherland-Hodgeman polygon clip

- Recall: polygon is convex if any line joining two points inside the polygon, also lies inside the polygon; implies that a point is inside if it is on the right side of each edge.
- Clipping each edge of a given polygon doesn't make sense - how do we reassemble the pieces? We want to arrange doing so on the fly.
- Clipping the polygon against each edge of the clip window in *sequence* works if the clip window is *convex*.
- (Note similarity to Sutherland-Cohen line clipping)

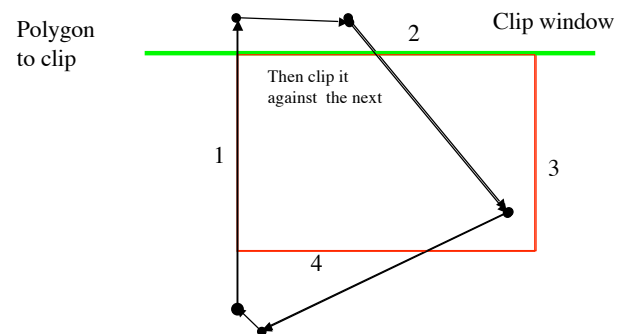
Sutherland-Hodgeman polygon clip



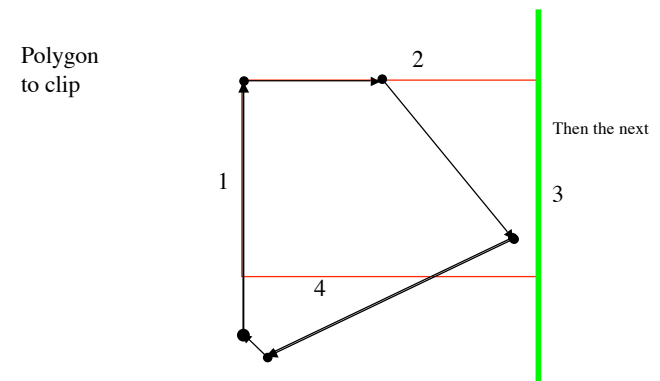
Sutherland-Hodgeman polygon clip



Sutherland-Hodgeman polygon clip

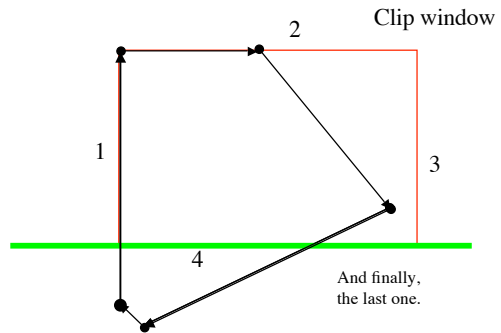


Sutherland-Hodgeman polygon clip

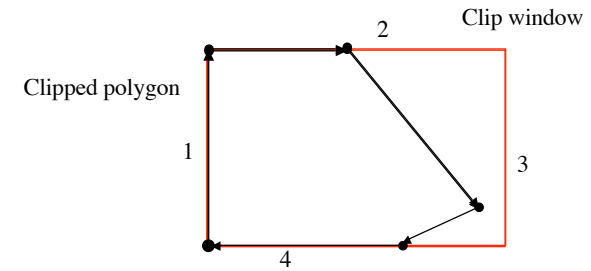


Sutherland-Hodgeman polygon clip

Polygon to clip

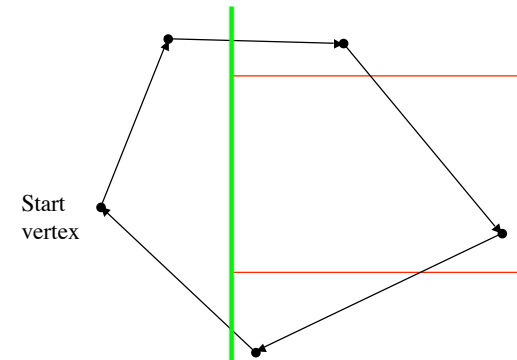


Sutherland-Hodgeman polygon clip

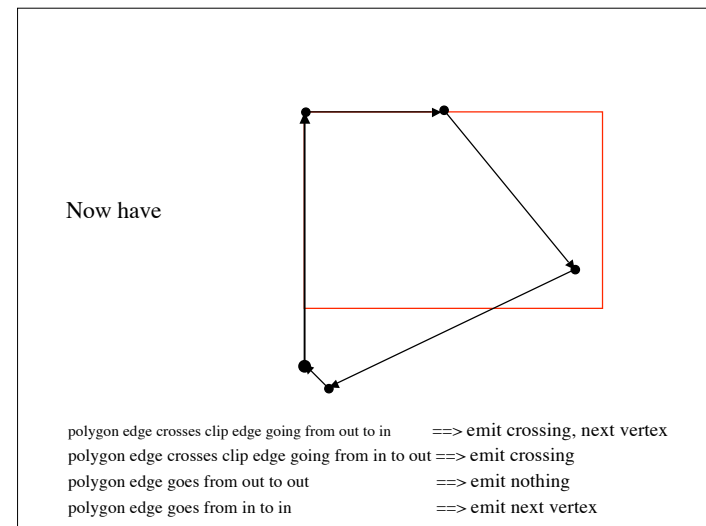
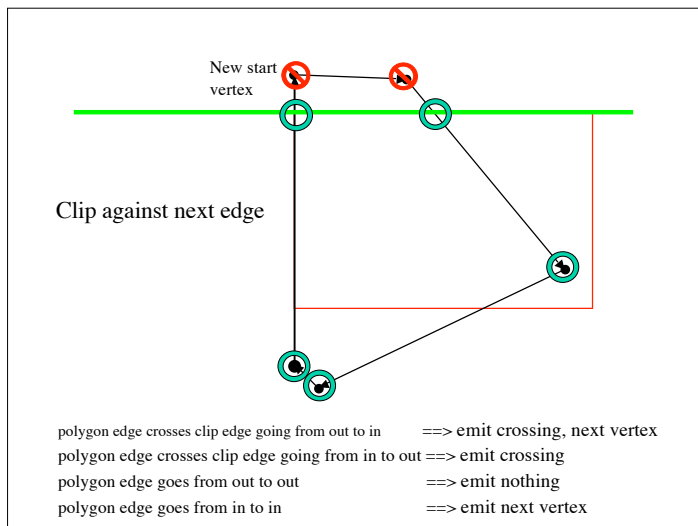
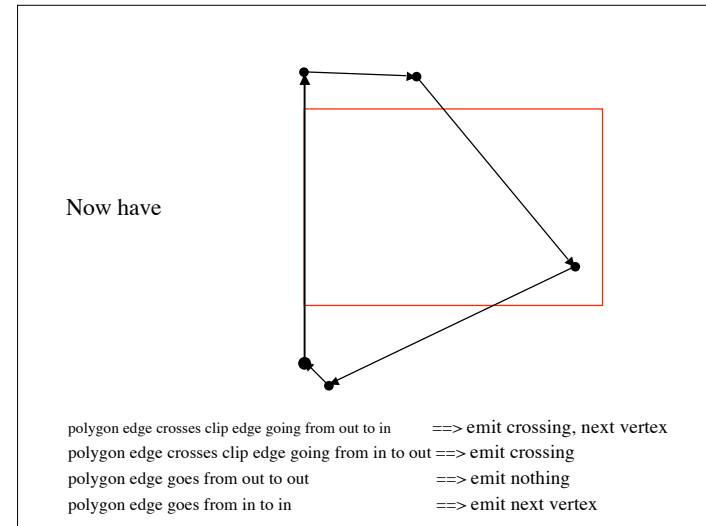
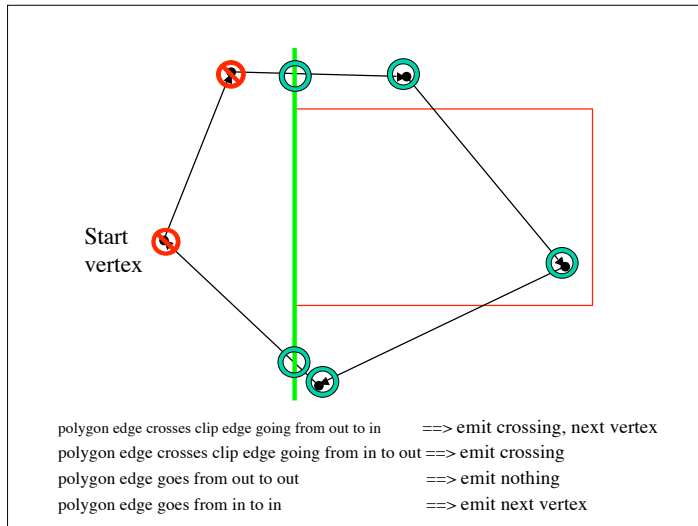


Clipping against current clip edge

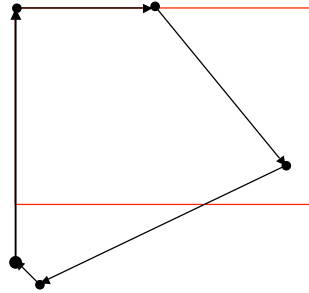
- Polygon is a list of vertices
- Think of process as rewriting polygon, vertex by vertex
- Check start vertex
 - in - emit it
 - out - ignore it
- Walk along vertices and for each edge consider four cases and apply corresponding action.
 - Four cases:
 - polygon edge crosses clip edge going from out to in
 - emit crossing, next vertex
 - polygon edge crosses clip edge going from in to out
 - emit crossing
 - polygon edge goes from out to out
 - emit nothing
 - polygon edge goes from in to in
 - emit next vertex



- polygon edge crosses clip edge going from out to in ==> emit crossing, next vertex
- polygon edge crosses clip edge going from in to out ==> emit crossing
- polygon edge goes from out to out ==> emit nothing
- polygon edge goes from in to in ==> emit next vertex

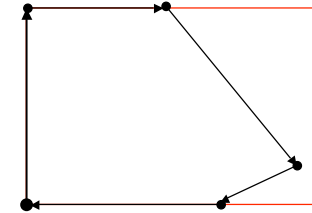


Clipping against
next edge (right)
gives



polygon edge crosses clip edge going from out to in ==> emit crossing, next vertex
 polygon edge crosses clip edge going from in to out ==> emit crossing
 polygon edge goes from out to out ==> emit nothing
 polygon edge goes from in to in ==> emit next vertex

Clipping against
final(bottom)
edge gives



polygon edge crosses clip edge going from out to in ==> emit crossing, next vertex
 polygon edge crosses clip edge going from in to out ==> emit crossing
 polygon edge goes from out to out ==> emit nothing
 polygon edge goes from in to in ==> emit next vertex

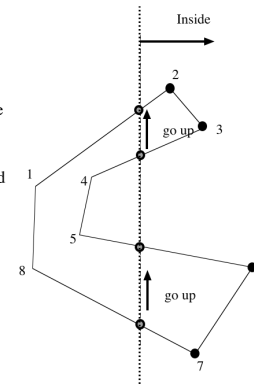
More Polygon clipping

- Notice that we can have a pipeline of clipping processes, one against each edge, each operating on the output of the previous clipper -- substantial advantage.
- Unpleasantness can result from concave polygons; in particular, polygons with empty interior.
- Can modify algorithm for concave polygons (e.g. Weiler Atherton)

Weiler Atherton

For clockwise polygon (starting outside):

- For out-to-in pair, follow usual rule
- For in-to-out pair, follow clip edge (clockwise) and then jump to next vertex (which is on the outside) and start again
- Only get a second piece if polygon is convex



Additional remarks on clipping

- Although everything discussed so far has been in terms of polygons/lines clipped against lines in 2D, all - except Nicholl-Lee-Nicholl - will work in 3D against convex regions without much change.
- This is because the central issue in each algorithm is the inside outside decision as a convex region is the intersection of half spaces.
- Inside-outside decisions can be made for lines in 2D, planes in 3D. e.g testing $dx \cdot n \geq 0$
- Hence, all (except N-L-N) can be used to clip:
 - Lines against 3D convex regions (e.g. cubes)
 - Polygons against 3D convex regions (e.g. cubes)
- NLN could work in 3D, but the number of cases increases too much to be practical.