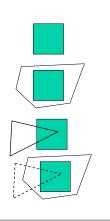
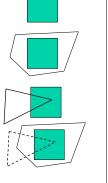
Area subdivision

- Four tractable cases for a given region in image plane:
 - no surfaces project to the region
 - only one surface completely surrounds the region
 - only one surface is completely inside the region or overlaps the region
 - a polygon is completely in front of everything else in that region, where this can be determined by considering depths of the polygons at the corners of the region



Area subdivision

- · Four tractable cases for a given region in image plane:
 - no surfaces project to the region (paint background if needed, otherwise do nothing)
 - only one surface completely surrounds the region (paint surface)
 - only one surface is completely inside the region or overlaps the region (paint background if applicable and then scan convert region)
 - a polygon is completely in front of everything else in that region determined by considering depths of the polygons at the corners of the region (paint surface)



Area subdivision

- Algorithm:
 - subdivide each region until one of these cases is true or until region is very small
 - if case is true, deal with it
 - if region is small, choose surface with smallest depth.
 - determining cases quickly makes use of the same ideas in depth sort (depth sorting, bounding boxes, tests for which side of the plane), and the difficult cases are deferred by further subdivision.

One Subdivision Strategy

Area subdivision

- · Advantages:
 - can be very efficient
 - no over rendering
 - anti-aliases well (subdivide a bit further)
- · Disadvantages:
 - not necessarily the fastest

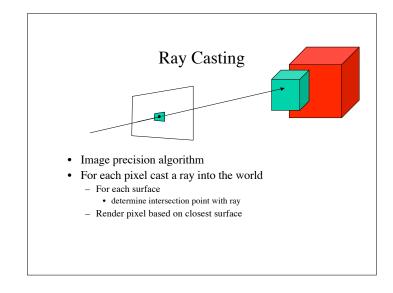
TABLE 15.3 RELATIVE ESTIMATED PERFORMANCE OF FOUR ALGORITHMS FOR VISIBLE-SURFACE DETERMINATION

Algorithm	Number of polygonal faces in scene		
	100	2500	60,000
Depth sort	1*.	10	507
z-buffer	54	54	54
Scan line	5	21	100
Warnock area subdivision	11	64	307

From Foley et al. page 716

Ray Casting

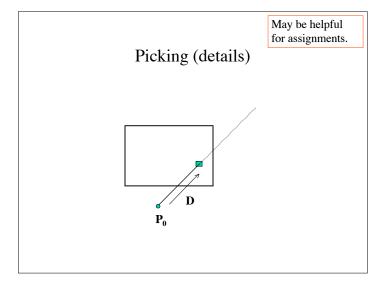
- · First step in ray tracing algorithm
- Expensive
 - Good performance usually requires clever data structures such as bounding volumes for object groups or storing world occupancy information in octrees.
- Very useful for "picking"--not expensive here (why?)
- Other than performance, main problem is computing intersection.
- · Our cleverly transformed spaces are less relevant
 - Canonical box and frustum were developed for other purposes.
 - Ray casting usually proceeds in original (of similar) coords.
 - For polygons, we could use the standardized orthographic space.
 - Spheres are normally easy (but not after any transformations that have made them non-spherical-careful!).



May be helpful for assignments.

Picking (details)

- Pick a polygon by shooting a ray from the focal point through a pixel
- (Many ways). Perhaps easiest to determine the ray in the space that you have after the first three transformations towards the canonical frustum.
 - Worried about performance due to transforming the world?
 Transform the pixel back to world coordinates.



Poly details

May be helpful for assignments.

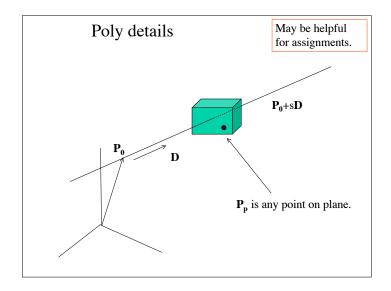
To find the intersection of the ray and the plane, solve:

$$\left(\mathbf{P_0} + s\mathbf{D} - \mathbf{P_p}\right) \bullet \mathbf{n} = 0$$

Once you have the point of intersection, P_i , test that it is inside by testing against all other faces indexed by j.

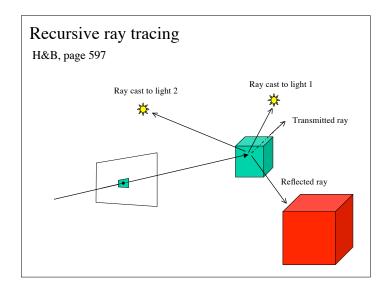
$$\left(\mathbf{P}_{i}-\mathbf{Q}_{j}\right)\bullet\mathbf{n}_{j}<0$$

Note that Q_i are on those *other* faces.



Ray Tracing--teaser

- Idea is very simple--follow light around
- Following **all** the light around is intractable, so we follow the light that makes **the most** difference
- · Work backwards from what is seen
- · Simple ray tracer
 - Cast a ray through each pixel (as in ray casting for visibility)
 - From intersection point cast additional rays to determine the color of the pixel.
 - · For diffuse component, must cast rays to the lights
 - · We may also add in some "ambient" light
 - For mirrors, must cast ray in mirror direction (recursion--what is the stopping condition)



Current state of intro students graphic's ability

Know how to draw polygons

Know about cameras

Know how to map 3D polygons onto the screen

Know how to draw the bits closest to the cameras

Issues

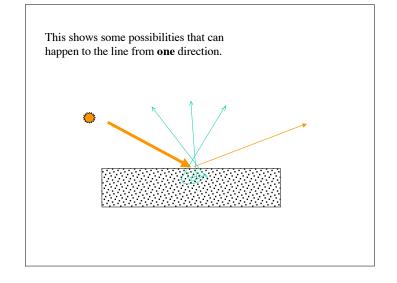
Should we live in a polygonal world?

How do you get polygons for complex objects?

What color should each pixel be?

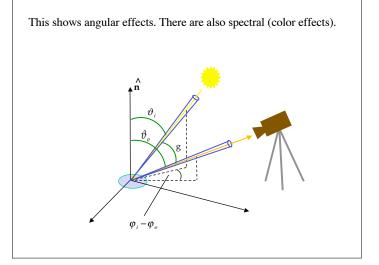
Light interacting with the world

- The signal reaching your eye from a surface is the result of the surface interacting with the light following on it.
- Many effects when light strikes a surface. It could be:
 - absorbed
 - transmitted
 - reflected
 - scattered (in a variety of directions!)



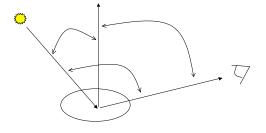
Bidirectional Reflectance Distribution Function (BRDF)

- The BRDF is a technical way of specifying how light from sources interacts with the matter in the world
- Understanding images requires understanding that this varies as a function of materials. The following "look" different
 - mirrors
 - white styrofoam
 - colored construction paper
 - colored plastic
 - gold
- The BRDF is the ratio of what comes out to what came in
- What comes out <--> "radiance"
- What goes in <--> "irradiance"
- Details on the BRDF available as supplementary material



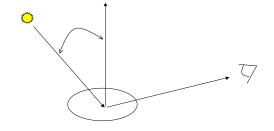
Isotropic surfaces

The BRDF for many surfaces can be well approximated as a function of 3 variables (angles), not 4. In this case, turning the surface around the normal has no effect. The surface is said to be *isotropic*.



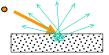
Lambertian surfaces

• Even simpler case--the BRDF does not depend on the viewing (output) direction (e.g., Lambertian).



Lambertian surfaces

- Simple special case of reflectance: ideal diffuse or matte surface--e.g. cotton cloth, matte paper.
- Surface appearance is independent of viewing angle.
- Typically such a surface is the result of lots of scattering---the light "forgets" where it came from, and it could end up going in any random direction.



• What counts is how much light power reaches the surface