

## Clustering using a generative statistical model

Associate each cluster with the same model type, but with different parameters.

Example (Gaussian Mixture Model (GMM)),

$$p(\mathbf{x}|c) = N(\mathbf{u}_c, \Sigma_c)$$

or, assuming feature independence,

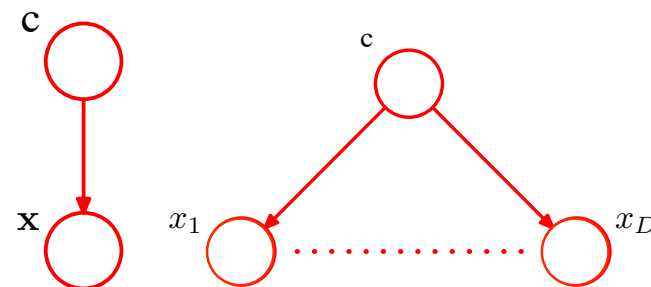
$$p(\mathbf{x}|c) = N(\mathbf{u}_c, \sigma_c^2)$$

$p(\mathbf{x}|c)$  could also be a product of independent multinomials, or, even a product of different distributions (roll your own!).

## Clustering using a generative statistical model

Graphical model

(and for independent features)



## Inference given a clustering

Given a learned clustering model (either supervised or unsupervised), we can compute a posterior probability of which cluster an instance belongs to.

$$p(c|\mathbf{x}) \propto p(\mathbf{x}|c)p(c)$$

Easily normalized since the number of clusters is limited:

$$p(c|\mathbf{x}) = \frac{p(\mathbf{x}|c)p(c)}{\sum_c p(\mathbf{x}|c)p(c)}$$

## Clustering models representing data statistics

What is the distribution of data best described by clusters?  
(Example, data coming from a bimodal distribution?)

$$\begin{aligned} p(\mathbf{x}) &= \sum_c p(\mathbf{x}, c) \\ &= \sum_c p(c) p(\mathbf{x}|c) \end{aligned}$$

Generative story:

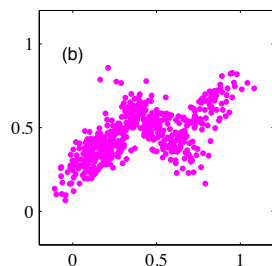
- 1) choose a cluster with probability,  $p(c)$ .
- 2) sample from  $p(\mathbf{x}|c)$ .
- 3) rinse and repeat.

## Clustering models representing data statistics

Distribution of data described by clusters.

$$p(\mathbf{x}) = \sum_c p(c) p(\mathbf{x}|c)$$

Distribution modeled 3  
multivariate Gaussians.



Even if we know the exact model, we cannot be sure from the data which point comes from which cluster. We only have the distribution for this.

## Learning the parameters from data

For concreteness, assume GMM

Assume K clusters

The goal is to learn mixing coefficients,  $p(c)$ , and cluster parameters for  $p(\mathbf{x}|c)$  for all K clusters indexed by  $c$ .

## Learning the parameters from data

The goal is to learn mixing coefficients,  $p(c)$ , and cluster parameters for  $p(\mathbf{x}|c)$  for all K clusters indexed by  $c$ .

From previous arguments, given  $p(\mathbf{x}|c)$ , we know the distribution over clusters for each data point.

Hence we simultaneously cluster and learn a cluster model.

## Learning the parameters from data

$$p(\mathbf{x}_i|\theta) = \sum_c p(c) p(\mathbf{x}_i|c, \theta_c)$$

Probability of all observed data will be the objective function

$$p(\{\mathbf{x}_i\}|\theta) = \prod_i \left( \sum_c p(c) p(\mathbf{x}_i|c, \theta_c) \right) \quad (\text{want this to be large})$$

or

$$\sum_i \log \left( \sum_c p(c) p(\mathbf{x}_i|c, \theta_c) \right) \quad (\text{should be large})$$

## Expectation Maximization (EM)

Operationally this is similar to K-means.

Observe that:

If we knew the cluster assignments,  
we could estimate the parameters for  $p(\mathbf{x}|c)$ .

If we knew  $p(\mathbf{x}|c)$ , we can make  
cluster assignments.

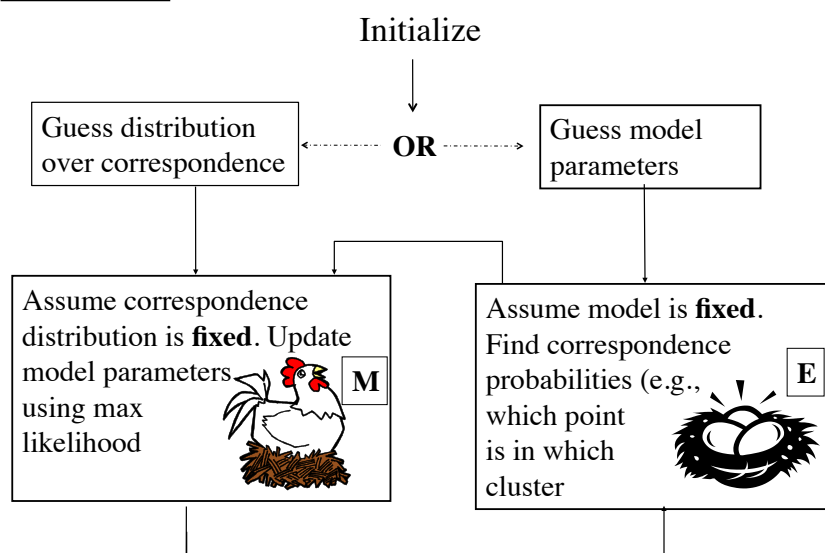
## Expectation Maximization (EM)

Difference with K-means.

We have **distributions** over the assignments,  $p(c|\mathbf{x})$ .

This leads us to work with expectations.

### EM flow chart



## EM for GMM

$$p(\mathbf{x}) = \sum_c p(c) p(\mathbf{x}|c) \quad \text{where} \quad p(\mathbf{x}|c) = \mathcal{N}(\boldsymbol{\mu}_c, \boldsymbol{\Sigma})$$

$$\boldsymbol{\Theta} = \{\boldsymbol{\Theta}_c\}$$

And, for multiple points

$$p(\{\mathbf{x}_i\}|\boldsymbol{\theta}) = \prod_i \left( \sum_c p(c) p(\mathbf{x}_i|c) \right)$$

This is our objective function.

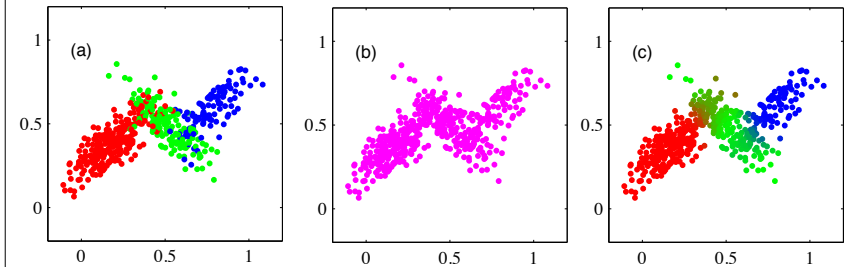
## EM for GMM

Assume we have estimates for the probability distribution over clusters for each point (the “egg”).

$$p(c | \mathbf{x}_i, \Theta^{(s)}) \quad (s \text{ indexes iteration (step)}).$$

These are called the responsibilities (of the cluster for the point).

## Responsibilities illustrated



## EM for GMM

- We estimate the mean for each segment naturally by:

$$\mu_c^{(s+1)} = \frac{\sum_{i=1}^n \mathbf{x}_i \cdot p(c | \mathbf{x}_i, \Theta_c^{(s)})}{\sum_{i=1}^n p(c | \mathbf{x}_i, \Theta_c^{(s)})} \quad (\text{weighted average})$$

- Variances/covariances work similarly

## EM for GMM

- Also, intuitively,

$$p(c) = \frac{\sum_i p(c | \mathbf{x}_i, \Theta^{(s)})}{\sum_c \sum_i p(c | \mathbf{x}_i, \Theta^{(s)})} = \frac{\sum_i p(c | \mathbf{x}_i, \Theta^{(s)})}{N}$$

We can sort out the chicken!



## EM for GMM

Given the parameters (the chicken), the probability that a given point is associated with each cluster is computed by:

$$p(c | \mathbf{x}_i, \Theta^{(s)}) = \frac{\pi_c^{(s)} \cdot p(\mathbf{x}_i | \Theta_c^{(s)})}{\sum_{c'} \pi_{c'}^{(s)} \cdot p(\mathbf{x}_i | \Theta_{c'}^{(s)})} \quad (\text{Note that we select } \Theta_c^{(s)} \text{ from } \Theta^{(s)}).$$

where  $\pi_c^{(s)} = p(c | \Theta_c^{(s)})$  i.e.,  $\pi_c^{(s)}$  is part of  $\Theta_c^{(s)}$ .

This is the cluster membership discussed before,

with less formal notation:  $p(c|x) \propto p(c)p(x|c)$

We can do the egg!



## EM illustrated

