## Review

## Factor Graphs

Suppose $\mathrm{p}(\mathbf{x})$ factorizes as:

$$
p(\mathbf{x})=\prod_{s} f\left(x_{s}\right) \quad \text { where } x_{s} \text { are sets of of variables within } \mathbf{x} \text {. }
$$

Make a node for each $x_{i}$ as usual.

Now, make a different kind of node for $f($ ) (e.g., squares).
Draw edges between the factor nodes and the variables in the variable set, $s$.

Note that the factorization formula means that we can convert both directed and undirected graphs to factor graphs.

## Review

## Factor Graph Summary

$p(\mathbf{x})=\prod f\left(x_{s}\right) \quad$ where $x_{s}$ are sets of of variables within $\mathbf{x}$.

Denote variables by circles

Denote each factor by a square
Draw links between squares and variables in the sets $x_{s}$.

Factor graphs are bipartite

Factor graph for a distribution is not necessarily unique.

## Review

## Factor Graph Example (2)



Review

## Trees/Polytrees

A directed graph is tree if the root node has no parents, others have exactly one parent.

An undirected graph is a tree if there is only one path between any pair of nodes.

A directed graph is a polytree if there is only one path per pair of nodes.


## Review

## Factor Graphs and Trees

Factor graphs for directed trees, undirected trees, and directed polytrees can all be trees.
(Recall definition for undirected trees---there is only one path between any two nodes).

This means that (variable) node, $x$, with K branches divides a tree into K subtrees whose factors do not share variables except $x$.

## Review

## Observations about factor graphs for trees

Any node can be root

Any node with K links splits the graph into K subgraphs which do not share nodes.

If we pass messages from:

1) the leaves to a chosen root;
2) the chosen root to the leaves,
then all messages that can be passed have been passed.
Further, the number of messages in 1 and 2 are the same.

## Review

Marginal distribution for a node $x$

$$
\begin{array}{rlrl}
p(x) & =\sum_{x / x} \prod_{s \in n(x)} F\left(x, X_{s}\right) & & \text { (marginalize) } \\
& =\prod_{s \in n(x)}\left\{\sum_{X_{s}} F\left(x, X_{s}\right)\right\} & & \text { (interchange sums and products) } \\
& & \text { (recall our fancy formula) } \\
& \left(\sum a_{i}\right)\left(\sum b_{j}\right)=\sum \sum a_{i} b_{j}
\end{array}
$$

Note that each sum is simpler than what we started with because the variable sets are disjoint except for $x$.

$$
\begin{aligned}
p(x) & =\sum_{\mathbf{x} / x} \prod_{s \in n(x)} F\left(x, X_{s}\right) \\
& =\prod_{s \in n(x)}\left\{\sum_{X_{s}} F\left(x, X_{s}\right)\right\} \\
& =\prod_{s \in n(x)} \mu_{f_{x} \rightarrow x}(x)
\end{aligned}
$$

$$
\mu_{f_{x} \rightarrow x}(x) \equiv \sum_{X_{s}} F\left(x, X_{s}\right) \quad \text { (factor-to-node message) }
$$

## Computing the factor $\rightarrow$ node messages



$$
\begin{aligned}
\sum_{X_{s}} F_{s}\left(x, X_{s}\right) & =\sum_{x_{1}} \sum_{x_{2}} \cdots \sum_{x_{M}} f_{s}\left(x, x_{1}, x_{2}, \ldots, x_{M}\right) \prod_{m \in n e\left(f_{s}\right) \backslash x} \sum_{X_{s m}} G_{m}\left(x_{m}, X_{s m}\right) \\
& =\sum_{x_{1}} \sum_{x_{2}} \cdots \sum_{x_{M}} f_{s}\left(x, x_{1}, x_{2}, \ldots, x_{M}\right) \prod_{m \in n\left(f_{s}\right) \backslash x} \mu_{x_{m} \rightarrow f_{s}}\left(x_{m}\right)
\end{aligned}
$$

where we define:
$\mu_{x_{m} \rightarrow f_{s}}\left(x_{m}\right) \equiv \sum_{X_{s m}} G_{m}\left(x_{m}, X_{s m}\right) \quad$ (node $\rightarrow$ factor messages)

Computing the factor $\rightarrow$ node messages

## The node $\rightarrow$ factor message

(We have defined)

$$
\mu_{x_{m} \rightarrow f_{s}}\left(x_{m}\right) \equiv \sum_{X_{s_{m}}} G_{m}\left(x_{m}, X_{s_{m}}\right)
$$

(For a node $x_{m}$ we send its distribution with the other variables in the subgraph marginalized out.)

Computing the node $\rightarrow$ factor message

| This is just like where we |
| :--- |
| started, but we exclude the |
| node we are sending to. Doing |
| the drill one more time $\ldots$ |


| $\mu_{x_{m} \rightarrow f_{s}}\left(x_{m}\right)$ | $=\sum_{X_{s_{m}}} G_{m}\left(x_{m}, X_{s_{m}}\right)$ |
| ---: | :--- |
| $=\sum_{X_{s_{m}}} \prod_{l \in n\left(x_{m}\right) \backslash f_{s}} F_{l}\left(x_{m}, X_{m l}\right)$ | (definition) |
| $=\prod_{l \in n\left(x_{m}\right) \backslash f_{s}} \sum_{X_{m l}} F_{l}\left(x_{m}, X_{m l}\right)$ | (exctors inside $\left.G_{m}\right)$ |
| $=\prod_{l \in n\left(x_{m}\right) \backslash f_{s}} \mu_{f_{l} \rightarrow x_{m}}\left(x_{m}\right)$ | where $\mu_{f_{l} \rightarrow x_{m}}\left(x_{m}\right)=\sum_{X_{m l}} F_{l}\left(x_{m}, X_{m l}\right)$ |



## Sum product on a slide



## The sum-product algorithm (1)

First, pass messages from leaves to root. If you just want more than one marginal or plan to do other computation, store the results.

Initialization: If leaf node is a variable node, then start with a unity message. If leaf node is factor, then start with the factor.


## The sum-product algorithm (2)

First, pass messages from leaves to root. If you just want more than one marginal or plan to do other computation, store the results.

Initialization: If leaf node is a variable node, then start with a unity message. If leaf node is factor, then start with the factor.

Note that all needed messages for computation will arrive at each node eventually.

The root node can compute the needed marginal.

## The sum-product algorithm (3)

To prepare for other computations (e.g, all marginals), pass messages from the root back to the leaves.

Because we just passed all messages to the root, the root has all the messages from its neighbors, and thus all it needs to compute the outward messages

Once we pass the messages back to the leaves, every node has all possible incoming messages on all its links, and can thus be considered the root.

Hence we can compute all marginals for twice the cost of computing one of them (from before, all messages that can be passed, have now been passed).

## The sum-product algorithm (5)

If the factor graph came from a directed graph, then the expression for $\mathrm{p}(\mathrm{x})$ is already normalized.

Otherwise (as was the case of the chain), we can determine the normalization constant by summing up one of the marginals (relatively inexpensive because only one variable is involved).

## Sum-product algorithm example

Let $\quad \tilde{\mathrm{p}}(\mathbf{x})=f_{a}\left(x_{1}, x_{2}\right) f_{b}\left(x_{2}, x_{3}\right) f_{c}\left(x_{2}, x_{4}\right)$


Declare $x_{3}$ as root node.

First we pass messages from leaves to root


$$
\begin{aligned}
& \mu_{x_{1} \rightarrow f_{a}}\left(x_{1}\right)=1 \\
& \mu_{f_{a} \rightarrow x_{2}}\left(x_{2}\right)=?
\end{aligned}
$$



(red colored $x_{i}$ are not the same as the ones in example!)

$$
\begin{aligned}
& \mu_{x_{2} \rightarrow f_{b}}\left(x_{2}\right)=\mu_{f_{a} \rightarrow x_{2}}\left(x_{2}\right) \mu_{f_{f_{\rightarrow}} \rightarrow x_{2}}\left(x_{2}\right) \\
& \mu_{f_{b} \rightarrow x_{3}}\left(x_{3}\right)=\sum_{x_{2}} f_{b}\left(x_{2}, x_{3}\right) \mu_{x_{2} \rightarrow f_{b}}\left(x_{2}\right)
\end{aligned}
$$

Summary of messages
from leaves to root
$\mu_{x_{1} \rightarrow f_{a}}\left(x_{1}\right)=1$
$\mu_{f_{a} \rightarrow x_{2}}\left(x_{2}\right)=\sum_{x_{1}} f_{a}\left(x_{1}, x_{2}\right)$
$\mu_{x_{4} \rightarrow f_{c}}\left(x_{4}\right)=1$
$\mu_{f_{c} \rightarrow x_{2}}\left(x_{2}\right)=\sum_{x_{4}} f_{c}\left(x_{2}, x_{4}\right)$
$\mu_{x_{2} \rightarrow f_{b}}\left(x_{2}\right)=\mu_{f_{a} \rightarrow x_{2}}\left(x_{2}\right) \mu_{f_{c} \rightarrow x_{2}}\left(x_{2}\right)$
$\mu_{f_{b} \rightarrow x_{3}}\left(x_{3}\right)=\sum_{x_{2}} f_{b}\left(x_{2}, x_{3}\right) \mu_{x_{2} \rightarrow f_{b}}\left(x_{2}\right)$


$$
\bigcirc_{f_{a}}^{x_{1}} \rightarrow \bigcap_{f_{b}}^{x_{2}} \rightarrow \underbrace{x_{3}}
$$

$$
\begin{aligned}
& t_{f_{f \rightarrow x_{2}}}\left(x_{2}\right) \\
& \mu_{x_{2} \rightarrow f_{b}}\left(x_{2}\right)
\end{aligned}
$$

Next we pass messages from root to leaves.

$$
\begin{aligned}
& \mu_{x_{3} \rightarrow f_{b}}\left(x_{3}\right)=1 \\
& \mu_{f_{b} \rightarrow x_{2}}\left(x_{2}\right)=\sum_{x_{3}} f_{b}\left(x_{2}, x_{3}\right)
\end{aligned}
$$



Candidate for third and fourth?

Lets go towards $x_{I}$ first.

$$
\mu_{x_{2} \rightarrow f_{a}}\left(x_{2}\right)=\mu_{f_{b} \rightarrow x_{2}}\left(x_{2}\right) \mu_{f_{c} \rightarrow x_{2}}\left(x_{2}\right)
$$

$$
\mu_{f_{a} \rightarrow x_{1}}\left(x_{1}\right)=\sum_{x_{2}} f_{a}\left(x_{1}, x_{2}\right) \mu_{x_{2} \rightarrow f_{a}}\left(x_{2}\right)
$$



Note use of saved message from going the other way.

Also, note that arrows define which link to exclude, and who gets the message. Factors are included irrespective of the direction of the blue arrows.

## Summary of messages


from root to leaves.
$\mu_{x_{3} \rightarrow f_{b}}\left(x_{3}\right)=1$
$\mu_{f_{b} \rightarrow x_{2}}\left(x_{2}\right)=\sum_{x_{3}} f_{b}\left(x_{2}, x_{3}\right)$
$\mu_{x_{2} \rightarrow f_{a}}\left(x_{2}\right)=\mu_{f_{b} \rightarrow x_{2}}\left(x_{2}\right) \mu_{f_{c} \rightarrow x_{2}}\left(x_{2}\right)$
$\mu_{f_{a} \rightarrow x_{1}}\left(x_{1}\right)=\sum_{x_{2}} f_{a}\left(x_{1}, x_{2}\right) \mu_{x_{2} \rightarrow f_{a}}\left(x_{2}\right)$
$\mu_{x_{2} \rightarrow f_{c}}\left(x_{2}\right)=\mu_{f_{a} \rightarrow x_{2}}\left(x_{2}\right) \mu_{f_{b} \rightarrow x_{2}}\left(x_{2}\right)$
$\mu_{x_{2} \rightarrow f_{c}}\left(x_{2}\right)=\mu_{f_{a} \rightarrow x_{2}}\left(x_{2}\right) \mu_{f_{b} \rightarrow x_{2}}\left(x_{2}\right)$
$\mu_{f_{c} \rightarrow x_{4}}\left(x_{4}\right)=\sum_{x_{2}} f_{c}\left(x_{2}, x_{4}\right) \mu_{x_{2} \rightarrow f_{c}}\left(x_{2}\right)$

## (similar to previous one)

$$
\begin{aligned}
& \mu_{x_{2} \rightarrow f_{c}}\left(x_{2}\right)=\mu_{f_{a} \rightarrow x_{2}}\left(x_{2}\right) \mu_{f_{b} \rightarrow x_{2}}\left(x_{2}\right) \\
& \mu_{f_{c} \rightarrow x_{4}}\left(x_{4}\right)=\sum_{x_{2}} f_{c}\left(x_{2}, x_{4}\right) \mu_{x_{2} \rightarrow f_{c}}\left(x_{2}\right)
\end{aligned}
$$



## Handling observed variables

Usually we have observed variables (e.g., evidence). We simply clamp those variables to their observed values.

More formally, denote hidden variables by $\mathbf{h}$, and observed ones by $\mathbf{v}$. Denote the observed value as $\hat{\mathbf{v}}$. For each observed variable, $v_{i}$, with value $\hat{v}_{i}$, we can introduce factors into the graph
$I\left(v_{i}, \hat{v}_{i}\right)= \begin{cases}1 & \text { if } v_{i}=\hat{v}_{i} \\ 0 & \text { otherwise }\end{cases}$
Then, $p(\mathbf{h}, \mathbf{v}=\hat{\mathbf{v}})=p(\mathbf{h}, \mathbf{v}) \prod I\left(v_{i}, \hat{v}_{i}\right)$ (needs to be normalized to get $p(\mathbf{h} \mid \hat{\mathbf{v}})$, but this Adds factor is easy since we are doing sum-product.)

